

Combi

OPERATING HANDBOOK



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Contents

| | Page |
|---|------|
| Contents | 1 |
| System Overview | 2 |
| General Specification | 4 |
| LED and LCD Indicators..... | 5 |
| Buttons and Lockout..... | 7 |
| Entering a password to get to User or Engineer mode | 8 |
| € Default Passwords | 8 |
| € COMBI System Menu Index (see appendix #1 for brief description) | 8 |
| Direct and Addressable Line text | 9 |
| Holding the Display..... | 9 |
| Testing the LEDs (7) and Relays (8) | 10 |
| Inhibiting a sensor (14)..... | 10 |
| Changing the direct gas type (18) | 10 |
| Gas Type Library | 11 |
| Event to remote relay (23) | 12 |
| Dimming the LEDs (11) | 12 |
| Mute the buzzer | 12 |
| Local and Remote relays | 13 |
| Modbus set up and indicators | 13 |
| Set Up Network | 14 |
| RS232 data log output | 15 |
| Event log (9) | 15 |
| Data to and from a PC using Hyper-terminal..... | 16 |
| Real Time Clock | 17 |
| Refresh Rate | 17 |
| Changing •Engineers• Password..... | 18 |
| Calibrating Gas Sensors | |
| € 16 direct 4-20mA gas sensors | 18 |
| € 64 Addressable gas sensors | 18 |
| € Cell replacement on Combi sensors - sensor calibration..... | 19 |
| Setting the Time to Alarm | 19 |
| Setting Alarm Levels..... | 19 |
| Setting number of Decimal Places | 19 |
| Setting the 4~20mA Deadband | 19 |
| Alarm Relay off timers | 20 |
| Voting Relays | 20 |
| Time Weighted Alarms | 20 |
| Defaulting Sections of the Panel | 21 |
| Default the Whole Panel from Power Up | 21 |
| Repeater (on CAN2 only)..... | 21 |
| Installation | 22 |
| € Siting the Sensors | |
| € Sensor Cable Routing | 24 |
| € Equipment Installation Guides | 25 |
| € Service ... Routine Attention | 28 |
| € Daily | 28 |
| € Twice-yearly Maintenance Schedule | 28 |
| € Action to be taken if the alarm activates | 28 |
| Appendix 1 (System Menu by number) | 29 |
| Appendix 2 (Image of typical PC-Panel-PC text file) | 35 |
| Appendix 3 (Modbus Register Specification for COMBI 16 channel + CAN system) | 37 |
| Appendix 4 (Event numbers) | 37 |
| Appendix 5 (Fuse Details) | 38 |
| Fig. 1 (PC adapter (converts sensor data output to RS232 for PC System Configuration) | 38 |
| Fig. 2 (System Configuration & Mainboard to sensor wiring Diagram) | 39 |
| Fig. 3 (Combi Controller Network Configuration)..... | 40 |
| Fig. 4 (Combi Circuit Boards)..... | 41 |
| Fig. 5 (System Wiring) | 42 |
| Fig. 6 (Enclosure Detail)..... | 42 |
| Set up procedure for Flammable sensors (C893) | f.43 |
| Set up procedure for Toxic sensors (C894) | f.45 |
| Auxillary Equipment | |
| Relay Switch Set-up C1179 | 47 |
| Channel 4~20mA C1147 | 48 |
| 4~20mA Input C1180 | 49 |
| Combi Sensor - location / Gas type - Log | f.50 |

N.B: (#) is the System menu option number

This document is non contractual and the equipment specification and detail may be modified at any time without prior notice.

System Overview

The COMBI is a 16 direct (4-20mA) plus 64 addressable channel gas monitoring system which displays gas concentration and constantly checks for alarm conditions.

Each channel consists of a remote gas sensor located at the point where gas is to be measured. The direct sensor types are individually wired back to the COMBI where as the addressable sensors can be connected to a shared CAN bus network minimizing cable requirements.

Each channel when connected becomes active and is recognized by the system and a fault occurs if it becomes disconnected. This allows a system to be activated on an individual sensor basis as commissioning takes place.

The gas types and alarm levels for Direct channels are set at the Combi panel but addressable types transmit this information to the panel. However, alarm levels for addressable sensors can be altered at the Combi panel or at the sensor itself.

Alarms can be individually set to be latched (requires reset button to clear) or unlatched (self clearing).

The panel can be powered from mains or 24V dc input with battery backup terminals. An output 24V 250mA terminal is available to power user devices. The battery input and mains voltage is monitored and will create a fault if the voltage is too low but the user has the option to disable these faults.

The Combi panel controls most actions and its dimmable backlit LCD display is capable of indicating the state of gas measurements or fault conditions. Likewise, dimmable LEDs internal and external give additional status information.

Many parameters including a text description of the location of a sensor are programmable via user and engineer's menus and retained when power is off. These parameters are reloaded at the next power up so that the system will perform as it did previously. The Combi panel also has two RS485 Modbus channels and can send data when requested to do so to a Modbus master controller thus allowing independent system management facilities.

Engineering menus allow for diagnostic monitoring of the Modbus transmit and receive buffers. A remote repeater can also be connected which allows the LCD, LEDs and buttons to be located elsewhere on a CAN bus as well as remaining functional on the main panel. A network controller can also be connected which appears as a repeater but to multiple panels connected to the CAN bus. A real time clock keeps track of time and this time value is displayed on the LCD and appended to any panel events such as alarms or faults etc. These events are retained in a 99 event memory which can be viewed on the LCD or sent to a PC via the RS232 channel. Likewise this RS232 channel can accept setup parameters from a PC and if needed can send the Combi parameters to the PC as a simple text file which can be edited. Text is sent out via the RS232 channel as an additional data logging facility. Events and gas level changes are the main types of data presented which the user can capture using HyperTerminal (or similar) on a PC.

The current time is transmitted via the CAN bus and any addressable sensor will receive it. Those addressable sensors with a local LCD display will show this time in addition to the gas concentration data etc.

- If multiple panels are connected on CAN bus, then the panel with the lowest address will send the time to the other panels.

Sensors connected on the CAN bus can have their address changed using **ENGINEER•S** menu 27 (Described in appendix:1).

Please note:

Connected sensors are recorded as present by the panel.

If a sensor is removed, and then the panel is switched on, a fault will occur showing the missing sensor.

Use **ENGINEER•S** menu 16 to clear all addresses if required.

Button action on the Combi panel can be protected by a Key lockout connection to prevent misuse. However, muting the buzzer which sounds if an event occurs can still be silenced by pressing the **ACCEPT** button **(1)**.

On board relays with voltage free contacts indicate alarm and fault states and additionally these relays are used for voting whereby sensors can be grouped and the relay is activated when a number of sensors have gone into alarm. The last four relays labeled OPT5, 6, 7 and 8 can also be used for time weighted average alarms covering the requirements of 15 minute and 8 hour measurements. Additionally, all 8 onboard relays and the first 16 of the external relays have a programmable delay to de-energise parameter which for example allows for fan evacuation of a space containing detected gas. These relays and the first 16 relays on the remote relay board can be set to be normally energised or de-energised.

Front panel LED•s indicate the general state of the panel. The red alarm LED will flash for new alarms until accepted/muted when it stays on constantly until reset. The amber fault LED comes on if a fault is present. If any sensor channel is inhibited the amber inhibit LED will be on.

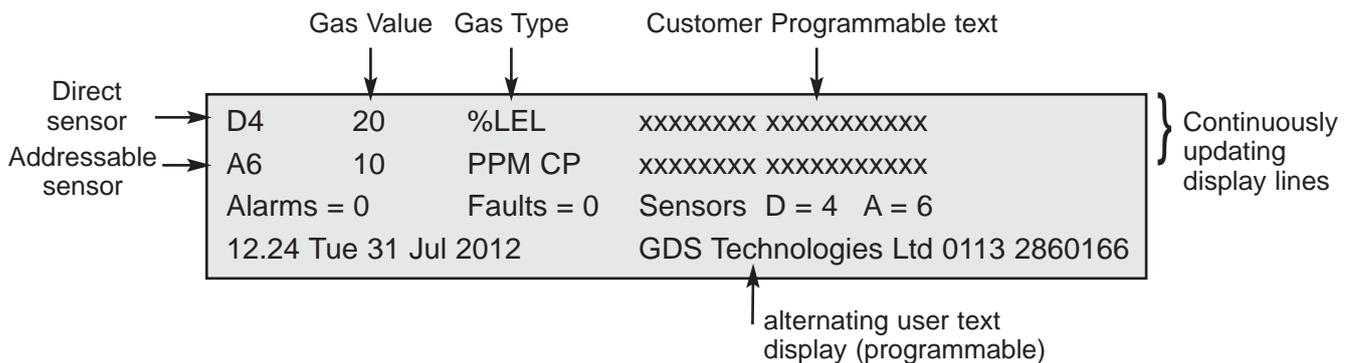
Additional reset and mute terminals are available to allow remote action in the event of an alarm or fault condition. Test facilities are included in the engineer•s menu, which allow these relays to be manually activated during commissioning.

General Specification

| | |
|---|--|
| Direct 4-20mA sensors | 16 Sensor Inputs (maximum) - source 2 Wire sensor Power = 0.6W 3 Wire sensor Power = 1.7W |
| Addressable sensors | 64 Sensor inputs (maximum) (CAN network ... 4 wire) end of line termination required. 1.7W per sensor |
| Internal Sensor Supply (Loading) | 24V.DC ... 3A / 70W Systems exceeding 70W sensor load should be powered from an external 24V power source. (See auxiliary power pack [260W] Price code: 200-003) |
| Sensor types | Electrochemical - Infra Red - Pellister |
| Sensor cable | Addressable CAN bus, 4 Core 1.5mm screened Direct 2/3 core 0.5mm screened |
| Power supply | 230/115Vac 50/60Hz +/-15% 24-28Vdc or Battery (external charger) Power Board = 6 Watts Main processor board = 5 Watts (See 1 and 2 for sensor loading) |
| Indication | 4 line, 40 character LCD 3x Externally visible LEDs for •Fault•, •Alarm• and •Sensor Inhibit• PCB LED•s include: •DC Fail•, •AC Fail•, •Sensor Fail•, •CAN Fail•, •Modbus Fail•, •Watchdog•, •System Inhibit•, •O/R•, •Hi Alarm•, CAN1/2, RS232, and •24V•/•12V•/•5V• rails |
| User Interface | 7 Buttons on main board and or repeater (Up, Down, -, +, Select, Dim, Reset) |
| Alarm settings | 3 Alarm levels which are user selectable High, Low, and Over range |
| Combi Panel Outputs | RS232 data log, (up to 10 meter) CAN bus (up to 1Km) Modbus slave to an external Modbus Master (up to 1Km @ 9600 baud) Optional Relay card (up to an additional 64 relays) Common Low alarm relay DPCO or •Group 1• Common High alarm relay DPCO or •Group 2• Common Over Range alarm relay SPCO or •Group 3• Fault relay SPCO or •Group 4• OPT G5 LTEL/STEL relay SPCO or •Group 5• OPT G6 LTEL/STEL relay SPCO or •Group 6• OPT G7 LTEL/STEL relay SPCO or •Group 7• OPT G8 LTEL/STEL relay SPCO or •Group 8• Sounder relay SPCO (Relays Lo, Hi and OR can be latched or unlatched) (Groups and LTEL/STEL relays can only be unlatched) |
| Relay rating | 5A@250Vac none inductive / capacitive |
| Audible | Mutable Buzzer on both Motherboard and Front panel Remote sounder (optional) |
| Dimensions | (H) 265mm x (W) 315mm x (D) 100mm |
| IP rating | IP52 optional IP65 |
| Enclosure | Mild steel powder coat BS00A01 IP52 (optional IP65) |
| Cable entry | Bottom / Rear 20mm push-outs |
| Weight | 5Kg |
| Terminals | Field terminals 2.5mm |
| Operating temperature | 5 to 40 C |
| Features | Remote reset Keylock Remote repeater panel (option) operating distance 1km 16way 4-20mA catalytic converter panel (option) Multiple panels using the network controller (option) 32 way CAN relay panel (option) |

LED and LCD indicators

A four line 40 character LCD displays a range of information typically shown below.



Line 1 Standard 4~20mA sensor, values and gas type and location

Line 2 Addressable sensor, values and gas type and location

Line 3 General information, Number of Alarms, Faults and Connected sensors

E.g. D=4 means 4 direct sensors connected

E.g. A=6 means 6 addressable sensors connected

Line 4 Date and Time alternating with user text.

The top line displays the direct 4~20 inputs indicated by D. This will cycle through all active sensors automatically but will hold on a specific sensor if it is in alarm.

Pressing **+** button **(4)** will stop the cycle on the current sensor for 999 seconds.

If a new alarm occurs, the display will show this sensor.

The type of gas and the text associated with this sensor is displayed.

To restart the cycle press the ...button **(2)** or **RESET (7)**

The second line displays addressable inputs indicated by A. this will cycle through all active addressable (CAN) sensors automatically but will hold on a specific sensor if it is in alarm. Pressing **+** button **(4)** will stop the cycle on the current sensor for 999 seconds.

If a new alarm occurs, the display will show this sensor.

The type of gas and the text associated with this sensor is displayed.

The third line displays the number of alarms and faults present in the Combi system.

Normally these are zero. Additionally, the number of 4-20 and Addressable sensors in the system are displayed.

The fourth line displays shows the internal clock reading together with the day and date. All internal events use this clock to record the time of event.

If an alarm or fault event occurs, the clock display is substituted with the text for this event and will alternate every second or so if the text is lengthy but will remain readable.

This text which describes the event (e.g. Modbus fail) is also the same text which is stored in the event log which can be viewed separately. (see Event Log).

This line also alternates with user text, eg company name and telephone number.

The **LEDs local to the panel** are as follows:

| Alarm | Internal/ External | Colour | Description |
|----------------|-------------------------------|---------------|--|
| Or Alarm | I | Red | on if any sensor currently has an over range alarm |
| Lo Alarm | I | Red | on if any sensor currently has a low alarm |
| Hi Alarm | I | Red | on if any sensor currently has a high alarm |
| DC fail | I | Amber | on if battery is low |
| AC fail | I | Amber | on if mains has failed |
| Sensor fail | I | Amber | on if any sensor has failed |
| CAN fail | I | Amber | on if any addressable sensor has stopped communicating |
| Modbus fail | I | Amber | on if the Modbus master has stopped communicating |
| System Inhibit | I | Amber | on if the system is not checking alarms |
| Sensor Inhibit | X | Amber | on if any sensor has been inhibited |
| Watchdog | I | Amber | on if the processor has had a watchdog reset |
| Power | I | Green | on if power applied |
| Fault | X | | on if a fault exists |
| Alarm | X | | on if alarm exists |

(I = view internal X = view external)

If the fault or alarm LED is flashing, this indicates a new event and when accepted by pressing the **UP (1)** button it remains on (not flashing).

Buttons and Lockout

7 user buttons are provided on the front to allow control and setting up of the Combi system plus there is an internal PCB button. These buttons are also numbered and shown in brackets. e.g. button 3 is **(3)**.

Button 1 is the **Accept/Mute** and **UP** button. When in engineer's mode, it is used to increment parameters which are being modified. Also, it allows the displayed sensor to be moved onto the next active sensor.

Button 2 is the **•-Z** button. Used when decrementing items in engineer's menu, also to escape from the engineers menu system when not in any specific menu.

Button 3 is the **SELECT** button. It is used to enter and exit many of the engineer's menus. Also when first pressed, it prompts the entry of an engineer's password. When correct, the engineer's menu is displayed in which sub-menus can be selected by pressing the **SELECT (3)** button again.

Button 4 is the **•+Z** button. Pressing this allows the display to hold the automatic sequence of sensors being displayed for 999 seconds.

When in engineer's mode, it is used to increment parameters which are being modified.

Button 5 is the **DOWN** button. Used when decrementing items in the engineer's menu.

Button 6 is the **DIM** button. It is used for dimming the LED's and LCD backlight and will toggle between full brightness and the dim level previously set in the engineer's menu. DIM can be used at any time except when doing an LED test whereby automatic dimming occurs to reduce current.

Button 7 is the panel **RESET** and is used to clear faults or alarms. It is generally active and will act regardless of entry of passwords.

To prevent unauthorised use of the buttons, Key lock input is provided on the main processor PCB, and the buttons are locked out of use when this terminal is connected to 0V (adjacent terminal) Even when locked, the buzzer can still be muted by pressing the **ACCEPT** button **(1)**.

Processor reset button and a flash programming jumper are situated directly on the PCB and are not accessible from the front panel.

This button when pressed will restart the processor as if just powered up and should only be used in the event of a system crash. The jumper should be removed for normal operation.

Entering a password to get to User or Engineer's menus

To protect system parameters from being altered by unauthorised people. Two passwords have to be entered to gain access to available menus which allow changes to be made.

The first 4 button password is the **USER** menu and gives access to a limited set of menus, E.g. clock set, LED test etc. The second 4 button password is for the **ENGINEER'S** menu which gives access to all menus including the users. A sequence of 4 buttons is accepted as the entry for a password.

To start the entry of the password, press **SELECT (3)**.

The password display is shown on the LCD and each of the 4 buttons in sequence can now be pressed.

Default Passwords

The **USER** password is defaulted to **DOWN (5)** pressed 4 times.

The **ENGINEER S** password is defaulted to **+ (4)** pressed 4 times. (or as per customer requirement)

Changing the engineers password is described later.

The user password cannot be changed.

Combi System Menu Index See Appendix 1 for further details.

Note: User menu only contains items shown in red. Engineer's menu contains all items.

- 1 View Modbus Reg
- 2 **Set Clock**
- 3 Inhibit all Sensors
- 4 View Modbus txrx
- 5 Refresh Rate
- 6 Edit Company Text
- 7 **Lamp Test**
- 8 Relay Test
- 9 **Event Log to LCD**
- 10 Add zero/span
- 11 **LCD LED Bright**
- 12 **Exit**
- 13 Top of Engineers
- 14 Inhibit Sensor
- 15 Add Alarm Levels
- 16 Clear All Addresses
- 17 Alter Chan Text
- 18 Alter Gas Type and Range
- 19 View Add sensor status
- 20 4-20mA Zero Span
- 21 4-20mA Alarm Levels
- 22 Unlatched Alarms
- 23 Event to Relay64
- 24 Relay off Timers
- 25 Channel Voting
- 26 Seconds to Alarm
- 27 Setup Network
- 28 Event log to PC
- 29 Data PC to Panel
- 30 Data Panel to PC
- 31 Ltel Stel Alarm
- 32 Default Sections
- 33 Engineer Password
- 34 Set Modbus Baud
- 35 Set Power Alarms
- 35 Set Power Alarm
- 36 Energised Relays

Direct and Addressable Line text

The Combi system measures data on all active sensors.

Direct sensors are done sequentially but addressable sensors send their data periodically when available (every few seconds).

Each sensor has a text description (stored on the main pcb, not in the sensor) which describes physically where it is in the system and this text appears on the LCD as the most recent measurement is displayed. Using the engineer's menu, this text can be altered from the default text to something more meaningful.

Editing this text is either manual using buttons and the LCD or by sending a text file from the PC. The latter is much faster and is preferred. The manual mode is activated from **ENGINEER'S** menu 17 which presents the direct 4-20 channels text first followed by the Addressable text.

Pressing **+** (4) or ... (2) changes which channel is to be altered and pressing **UP** (1) enters the text editing mode for this channel. The **+** (4) and ... (2) buttons now move a cursor under the text and **UP** (1) and **DOWN** (5) alter the character at this cursor position. When editing is finished for this channel, press **SELECT** (3) to exit the editing which returns to allow changes on another channel by pressing the **UP** (1) button again. Alternately pressing **SELECT** (3) will exit the direct 4-20 channel text and enter the Addressable channel text selection. Again the buttons are used in exactly the same way to change the text description for networked Addressable sensors.

SELECT (3) when pressed will exit the manual mode and save the text changes in non volatile memory on the main PCB and return to the **ENGINEER'S** menu.

See also DATA to and from a PC using Hyper-terminal which allows a much quicker method of editing using a PC.

Holding the Display

As the display cycles through the active sensors sequentially, it may be required to stop on a particular channel for maintenance.

This can be achieved using the **+** (4) button on the front panel which when pressed will hold the current sample for 999 seconds. A countdown is displayed on the LCD showing that hold is in progress. At the end of this time normal display sequencing will resume.

The gas values displayed on the LCD during hold are still the current live readings from the sensors.

Hold can be removed at any time by pressing the **+** (4) button for a second time.

As the sequence of display continues it is sometimes required for maintenance to choose another sensor for display and this can be achieved using **UP** (1).

This button when pressed terminates the current display it moves to the next displayed channel and if pressed continuously, this button will step through all available sensors

When the desired channel is reached and the button released, press **+** (4) to hold this display for 999 seconds. Pressing **+** (4) will release the system back to normal.

Testing the LEDs (7) and Relays (8)

To test all LEDs and beep the buzzer, use menu number 7 and press **SELECT (3)** to make all LEDs illuminate in dimmed mode to see if they are functioning. At the end of the test, the buzzer beeps twice to confirm its operation.

Note: some diagnostic LEDs on the main PCB are not part of this test. In particular these are, Modbus, RS232 and CAN active. These LEDs are only illuminated when transmitting data from the Combi panel.

When a remote relay board is present in the system, each of the 64 relays can be energised or de-energised using USER menu number 8.

When selected, use the **UP (1)** and **DOWN (5)** buttons to choose a relay and then the **+** **(4)** and **...** **(2)** buttons to energise or de-energise respectively.

When finished, use the **SELECT (3)** button to return to the **USER** menu.

Inhibiting a sensor (14)

During maintenance, it is sometimes required to inhibit the alarms on a particular sensor. A front panel LED will illuminate if any sensor is inhibited.

Choosing **ENGINEER•S** menu 14, the **UP (1)** and **DOWN (5)** buttons select which of the direct 4-20 inputs will be inhibited. The **+** **(4)** and **...** **(2)** buttons are used to turn the inhibit ON and OFF respectively.

Pressing **SELECT (3)** moves the selection to the CAN networked sensors and the buttons are used in the same way.

Pressing **SELECT (3)** again returns to the **ENGINEER•S** menu.

Changing the direct gas type (18)

Each of the sixteen 4-20mA inputs can have a different gas type which can be changed using **ENGINEER•S** menu 18.

When selected, buttons **+** **(4)** and **...** **(2)** change the channel number and **UP (1)** and **DOWN (5)** will change the gas type (according to the Gas Type library).

There are 8 user definable gases (61 to 68) available in the Gas Type library. When one of these is selected pressing **DIM (6)** allows the user to name the gas using **UP (1)** and **DOWN (5)** to sequentially change the alphanumeric characters and **+** **(4)** and **...** **(2)** to move the cursor beneath the characters. Pressing **SELECT (3)** saves the name and returns to gas selection menu.

Pressing **RESET (7)** changes this menu to allow the maximum value of a gas to be changed. The **+** **(4)** and **...** **(2)** buttons will change the displayed value. Pressing **SELECT (3)** will return to the **ENGINEER•S** menu.

Note: that it is not possible to change the gas type for addressable sensors from the Combi panel. The gas type is set at the sensor itself and the Combi panel displays the information received from the sensor.

Gas Type Library

| | | |
|--------------|----|---|
| O2 | 1 | Oxygen 0-25% two falling alarms |
| CO2 | 2 | Carbon Dioxide 1000ppm |
| CO2b | 3 | Carbon Dioxide 0-30%V |
| CO2a | 4 | Carbon Dioxide 0-2%V |
| H2S | 5 | Hydrogen Sulphide 0-50ppm |
| CO | 6 | Carbon Monoxide 0-250ppm |
| SO2 | 7 | Sulphur Dioxide 0-10ppm |
| NO | 8 | Nitrous Oxide 0-100ppm |
| NO2 | 9 | Nitrogen Dioxide 0-10ppm |
| Cl2 | 10 | Chlorine 0-10ppm |
| H2 | 11 | Hydrogen 0-1000ppm |
| HCN | 12 | Hydrogen Cyanide 0-25ppm |
| HCL | 13 | Hydrogen Chloride 0-10ppm |
| NH3 | 14 | Ammonia 0-100ppm |
| O3 | 15 | Ozone 0-2ppm |
| C2H4O | 16 | Ethyene Oxide 0-25ppm |
| CH4 | 17 | Methane 0-1000 ppm |
| PH3 | 18 | Phosphene 0-2ppm |
| LPG%Vol | 19 | Propane %volume |
| BUT%Vol | 20 | Butane %volume |
| FLAM%Vol | 21 | Flammable %volume |
| LPG%LEL | 22 | Propane %lel |
| BUT%LEL | 23 | Butane %lel |
| FLAM%LEL | 24 | Flammable %lel |
| WATER | 25 | 0-100% |
| COb | 26 | Carbon Monoxide 0-1000ppm |
| NH3ppm | 27 | Ammonia 1000ppm |
| NH3%vol | 28 | Range 5.0%volume |
| HF | 29 | Hydrogen Flouride 0-10ppm |
| Temp | 30 | Temperature -5 to +50 C |
| UgM3 | 31 | Microgram per metre cubed oil mist |
| B2H6 | 32 | Diborane 0-1ppm |
| SiH4 | 33 | Silane 0-5ppm |
| Ph3b | 34 | Phosphene 0-1ppm |
| F2 | 35 | Flourine 0-5ppm |
| NF3 | 36 | Nitrogen Triflouride 0-50ppm |
| LEL%/M | 37 | LEL per metre, 0-5% |
| SW Input | 38 | Switch input 0-100% (Displays as SW input when not in Alarm, and SW Active when in Alarm. Note: use channel text to describe this switches function). |
| refrig | 39 | 0-1000ppm refrigerant (e.g. R22) |
| benzine | 40 | Benzine 0-100%LEL |
| flame | 41 | flame detector 0-100% |
| fire | 42 | fire detector 0-100% |
| humid | 43 | humidity detector 0-100% |
| smoke | 44 | smoke detector 0-100% |
| callpoint | 45 | callpoint detector 0-100% |
| H2 | 46 | Hydrogen 0-2000ppm |
| CS2 | 47 | Carbon Disulphide 0-100ppm |
| H2s | 48 | Hydrogen Sulphide 0-100ppm |
| NH35000 | 49 | NH3 5000ppm |
| AcrylNitrile | 50 | Acryl Nitrile 0-25ppm |
| HCL | 51 | Hydrogen Chloride 0-30ppm |
| Sih4 | 52 | Silane 0-50ppm |
| NH3200 | 53 | Ammonia 0-200ppm |
| VOC20 | 54 | 0-20ppm |
| VOC100 | 55 | 0-100ppm |
| VOC1000 | 56 | 0-1000ppm |
| H2%LEL | 57 | H2 Flam 0-100%LEL |
| CO2_2000 | 58 | CO2 0-2000ppm |
| HEXNEPPM | 59 | 0-1000ppm |
| Usergas1 | 61 | - |
| Usergas2 | 62 | - |
| Usergas3 | 63 | - |
| Usergas4 | 64 | - |
| Usergas5 | 65 | - |
| Usergas6 | 66 | - |
| Usergas7 | 67 | - |
| Usergas8 | 68 | - |

Event to remote relays (23)

The following events can be assigned to remote 1-64 relays by using **ENGINEER•S** menu 23.

| | | |
|-------------------|------|---------|
| 4-20 direct | chan | fail |
| 4-20 direct | chan | hialarm |
| 4-20 direct | chan | loalarm |
| 4-20 direct | chan | oralarm |
| CAN | chan | fail |
| CAN | chan | hialarm |
| CAN | chan | loalarm |
| CAN | chan | oralarm |
| COMM | fail | alarm |
| Main power | fail | |
| CAN bus | fail | |
| Battery / Standby | fail | |

Pressing **SELECT** (3) moves to each of these event groups and using **UP** (1) and **DOWN** (5), the channel can be chosen and the **+** (4) and **-** (2) buttons decide which relay is to be operated. Note that it is possible to not drive any relay which is the default and this is indicated on the LCD as relay O.

Pressing **DIM** (6) at this point allows relay patterns to be entered which will be output to the external relays if this event occurs.

Pressing **SELECT** (3) eventually returns to the **ENGINEERS** menu after saving the selections and these relays will now energise when the event occurs.

Dimming the LED•s (11)

The LED•s on the main processor board and the LCD display are normally bright but can be dimmed to give a more acceptable level of illumination in subdued control room conditions.

The **DIM** (6) button on the main panel when pressed will toggle the brightness between maximum and dimmed for both. The level to which dimming occurs can be set via the User Menu number 11. This shows the current brightness setting and then using the **UP** (1) and **DOWN** (5) buttons a new dim level can be set and this is shown on the LCD and on the LEDs themselves. This dim value is stored in non-volatile memory for future use and subsequent power ups. In addition to dimming the LED•s, the LCD backlight is also dimmed and to enable a balance between LCD brightness and LED brightness, a pot on the main PCB (RV2) allows LCD backlight adjustment. If a repeater is connected to the main panel then the dim levels are also activated using the same buttons on the repeater.

Mute the buzzer

When an alarm or fault condition occurs the buzzer on the main processor board will sound. By pressing the **ACCEPT** button (1) on the front panel, the buzzer will become silent. **Note:** even if the key lock terminal is active to prevent button entry, the mute function will still silence the buzzer. A jumper near the buzzer on the PCB allows the buzzer to be isolated, this jumper should normally be fitted.

Local and Remote relays

Local relays are located on the main input PCB and are designated to specific conditions which exist within the Combi system and can be programmed to be normally energised.

Remote relays are located on one of two 32 channel relay boards and can be programmed to be operated according to detected events which occur such as alarms and faults. The first 16 relays can be programmed to be normally energised.

The local relays are as follows (all contacts are rated at 5A 250Vac)

Common Over range alarm will energise if any gas is over range. S.P.C.O

Common High alarm will energise if any gas is in high alarm. D.P.C.O

Common Low alarm will energise if any gas is in low alarm. D.P.C.O

Fault will de-energise if any fault exists in the system. S.P.C.O

Option 5 will energise if voting 5 conditions are met. S.P.C.O

Option 6 will energise if voting 6 conditions are met. S.P.C.O

Option 7 will energise if voting 7 conditions are met. S.P.C.O

Option 8 will energise if voting 8 conditions are met. S.P.C.O

Sounder Relay will energise if a new alarm occurs, and is de-energised when mute, **UP (1)**, is pressed

A small relay on the front panel energises if a sensor is inhibited.

This includes •power up inhibitŽ periods

The 64 additional remote relays which are S.P.C.O types can be programmed to operate on an event as an individual relay 1 to 64. Alternatively the first 16 relays can be programmed to use patterns. See **ENGINEER•S** menu 23 Event to Relay.

Modbus set up and indicators

Modbus is a means of obtaining data from the gas detection system via a MODBUS master controller. The Combi system is a SLAVE to the commands received from the master via two RS485 twisted pair communication cables. When a command is received on one of these cables, the reply is sent on the same cable thus giving rise to half duplex communication. For maintenance purposes, two LED•s situated on the main processor PCB close to the connectors show when a reply is being sent on that particular cable.

In a MODBUS system that makes use of both these cable, both these LED•s flash periodically to indicate successful communication. Once the communication has started, the Combi system will monitor how long since the last command was received and if this is greater than 50 seconds a communications failure (COMMS FAIL) alarm will occur.

Each Combi system has an internal address, which is used both for Modbus address and CAN bus address (see repeaters). This address and other parameters can be set and will be remembered at power up using **ENGINEER•S** menu 27 Setup Network. The speed of communication (baud rate expressed in bits per second) is set using menu 34.

All communicating devices in a Modbus system should be set to the same baud rate and the Combi system is capable of supporting 19200, 9600 and 4800 baud. 9600 is set by default.

Set up Network

The addresses of the network sensors are 1-64 so it is normal to have the Combi main panel address above this, the default address is 201. Using **ENGINEER•S** menu 27 (set up network), the address of the Combi can be changed using **UP (1)** and **DOWN (5)** buttons. Pressing **SELECT (3)** saves this address and presents a view of all other devices connected to the COMBI.

Using the UP (1) and DOWN (5) buttons each address in the system can be viewed and if a device exists, a letter will appear to tell you what device is connected.

The following table shows what type of device each letter represents:

- P = Combi Panel
- C = CAN Sensor
- R = Repeater or Network Controller
- I = 8 Channel 4~20mA Output Module
- S = 4 Relay + Sounder Module
- Z = 32 Relay Module

If a repeater is detected, the letter R will appear together with a •Y• or •N•, N means that you are not currently connected to the repeater.

Pressing + (4) will change the •N• to a •Y• to indicate connection and.. (2) will change back to no connection.

When the repeater is connected, the Combi will send text and LED data to it and accept button presses from the repeater thus allowing remote operation of the combi panel. Pressing **SELECT (3)** again returns to the **ENGINEER•S** menu.

Modbus baud rate

Using **ENGINEER•S** menu 34, the baud rate used by Modbus can be changed. Pressing **UP (1)** and **DOWN (5)** will alter the baud rate. Pressing **SELECT (3)** returns you to the **ENGINEER•S** menu.

The Modbus protocol for the data packets received from a master is usually a request for specific data to be sent back to the master. This protocol is covered in a separate document known as MODBUS RTU protocol. In its simple form, the master will ask for the data kept in any of the 250 registers located in the Combi system and the Combi will reply with the requested register data.

These registers are 16 bit numbers representing 0 to 65535 in decimal. A view of these registers can be seen by using **ENGINEER'S** menu 1. **UP (1)** and **DOWN (5)** will display different register numbers with the data. It is useful when first setting up the system. Additionally, **ENGINEER'S** menu 4 allows you to view the Modbus data packets received and transmitted. Again, this is used when first setting up the system and can diagnose requests and responses.

See Combi Modbus register definitions in the appendix.

RS232 data log output

In addition to Modbus, an additional data stream showing actions within the COMBI system is available via the RS232 output.

This consists of a 3 wire interface which can connect directly into the serial port (RS232) connection on a PC which is a 9 way D-type female connector (not supplied). This should be wired to the Combi system as follows.

| D-type Pin | COMBI RS232 connector (Bottom left of PCB) |
|------------|--|
| 2 | Tx |
| 3 | Rx |
| 5 | 0V |

Using Hyper-terminal on the PC set up at 2400 baud 8 bit no parity and no handshake, the data output should appear on the screen and consists of any text which is being recorded in the event log.

Event log (9)

The events listed in appendix 1 are logged internally in the COMBI system.

A total of 99 events can be stored and viewed later either on the LCD or on a PC using Hyper-terminal.

When this 99 event memory is full, the oldest event is replaced by the new event so this history of events always represents the last 99 incidents.

Using **ENGINEER•S** menu number 9, this event memory can be viewed one event at a time using the **UP (1)** and **DOWN (5)** buttons to scroll through the sequence. Date and time of the event is also displayed.

With the RS232 cable connected to the PC and Hyper-terminal in use at 2400 baud the whole event log can be sent using **ENGINEERING** menu 28.

Using capture text in Hyper-terminal, this event log can be saved to a file for future examination or printing etc.

Data to and from a PC using hyperterminal

Within the Combi system there are parameters which have to be set such as the text which describes the location of a particular sensor. Whilst these parameters can be set manually using the buttons, it is quicker and easier to send a text data file from a PC using the RS232 interface via Hyper-terminal (which is standard on a Windows XP PC).

The file which is sent is simple alphanumeric characters which can be edited using a simple text editor like Notepad which is also standard on a Windows PC.

This file can be created from scratch but it is simpler to create it by sending the data already stored on the Combi panel to the PC again using Hyper-terminal.

This method is now described followed by how to reload the file back into the Combi main panel.

Using **ENGINEER•S** menu 30 (Data panel to PC) and the RS232 lead plugged into the PC COM port.

On the PC, click (for Windows XP)

```
START
PROGRAMS
ACCESSORIES
COMMUNICATIONS
HYPERTERMINAL
```

and set the hyper-terminal to the active COM port, at 8 data bits, no parity, 1 stop bit, no handshake then select Transfer and Capture text, a filename is suggested to save the data to. You can change this filename as required and do take note of which directory it is going to be stored in, then press the start button and the PC is now waiting for data to be sent from the Combi system. (Note it is easier to save this file to the desktop initially).

Using **ENGINEER•S** menu 30 (Data panel to PC) press select which should send data to the PC. This data can be seen on the PC screen as it is transferred. When it is complete, on the PC use:

```
TRANSFER
CAPTURE
STOP
```

this saves the data onto the hard disk in the folder specified previously. Each line of text (shown in the table below) in this file forms particular data as follows:-

A line which does not start with a colon : or an asterisk * is ignored which allows you to add comments at any point in the text. Colon : indicates data for direct sensors, an asterisk * is used to indicate addressable sensors.

| Line | Description |
|------------------|---|
| :T6, Port Hold 1 | This line is the text for direct sensor 6 which will display on the LCD. For each direct input 20 characters can be assigned. |
| *T4, AccomBlock | This line is the text for addressable sensor 4 which will display on the LCD. For each of the 64 addressable sensors up to 20 characters can be assigned. |
| :G1,%LeL^ , | This line selects a gas type for gas sensor 1 appropriate gas sensor must be fitted in the system. All 16 direct types can be selected (Note: this does not apply to CAN addressable sensors as they transmit their gas type to the control panel.) |
| :HiAlarm 2,400 | The high alarm point for direct sensor 2 is 400 divided by 10 (40.0). High alarms can be set according to the type of gas and the value represents 10 times the actual value (this is to avoid decimal points in the data). |
| :LoAlarm 1,200 | Ditto for sensor 1 low alarm point. |
| :OrAlarm 3,998 | Ditto for sensor 3 over range alarm |
| :X | This terminates the text transmission to the panel and should always be at the end of the text. (Note: with the exception of :X, using *T, *H etc. sets the parameters for addressable sensors) Text lines after :X is ignored. If an :X is not included in the file then the panel will eventually time out but this may take a few minutes. |

Having edited the text to suit the installation, it can now be sent back to the panel using **ENGINEER•S** menu 29 PC to panel.

Again, Hyper-terminal is used but this time the Transfer/Send text file option is used.

When prompted, choose your modified text file as the one to send and then the text should start to flow. The output seen on the Hyper-terminal screen consists of the command letters received so strings of T or H, etc are seen which lets you know that all is well. The final letter seen will be an X and at this point the new data sent is stored in non volatile memory on the processor board.

Real time clock

On the main processor board a real time clock chip keeps time and this can be set using **USER** menu 2 in conjunction with the **UP (1)** and **DOWN (5)** buttons and **SELECT (3)**.

To ensure that the clock keeps time when no power is applied, a large value capacitor on the PCB provides power to the clock for up to 24 hours.

If the processor board is unpowered for longer than this, it is probable that the clock will have to be reset to local time before use.

It is important to keep the clock correct since this time is used when recording events in the event log and also for the RS232 output log to a PC.

Refresh Rate

The display of sensor gas levels on the display is cyclical.

ENGINEER'S Menu 5 allows you to change the amount of time that data is displayed; slower refresh rates tend to be used when the number of sensors is small. Using **+ (4)** and **... (2)** buttons this rate can be set to fast **•1•** to slow **•10•** or any number in-between.

Changing Engineer's Password

The passwords are present to prevent unauthorised button entry on the control panel and whilst the user password is fixed, the **ENGINEER'S** password can be changed. Using **ENGINEER'S** menu 33 will allow you to enter a new engineer's password. You are prompted to re-enter the new password again as a check and if both are the same then this password is the new engineers password.

Calibrating Gas Sensors (see setup procedure for sensors)

16 direct 4-20mA gas sensors ... source mode

Each of the external gas sensor cards has to be periodically calibrated with its sensor to produce a 4-20mA signal to input to the Combi (see sensor data sheets C893 & C894) This signal input to the Combi would produce a 0 to 100% of the signal range but a further level of calibration trimming is possible at the Combi panel.

To assist in this process, **ENGINEER'S** menu 20 adjust 4~20mA zero/span will guide you through the stages of calibration for these direct sensors.

The first step is to select which of the 16 sensors is to be calibrated.

Pressing **SELECT (3)** moves to the next step which is -

Set the maximum value expected from the sensor e.g. flam is 99.9% Pressing **SELECT (3)** moves to the next step which is -

Use the **UP (1)** and **DOWN (5)** buttons to adjust the zero on the LCD

Pressing **SELECT (3)** moves to the next step which is -

Apply span gas and use the **UP (1)** and **DOWN (5)** buttons to change the gain until the reading is correct on the LCD for the applied gas.

The gas values used in this case are the peak values from the sensors and this gives the ability to apply gas to a number of sensors before returning to the Combi panel to adjust thus allowing one engineer to set the span. In this case, the zero on these sensors should be completed before span is performed.

This completes the calibration of the direct 4-20mA gas sensor.

64 Addressable gas sensors

Use **ENGINEER'S** menu 10 (addressable zero span) on the Combi to calibrate the addressable sensors. The inhibit LED on all connected sensors will flash. Use the **UP (1)** and **DOWN (5)** buttons to look at all sensor addresses which are being zeroed and use the **+** **(4)** or **...** **(2)** buttons on Combi to zero the reading on each sensor.

Press the **SELECT (3)** button on Combi to enter the span mode which gives plenty of time to visit each sensor. Gas each sensor with appropriate calibration span gas and return to the Combi panel.

Use the **UP (1)** and **DOWN (5)** buttons to view each sensor address and using the **+** **(4)** or **...** **(2)** buttons, adjust the peak sensor reading to be that of the calibration gas. Press **SELECT (3)** to exit this menu when all sensors have been adjusted.

Note: peak readings are lost when exiting from this menu. Re-enter the menu and use again to calibrate any missed sensors.

Cell replacement on Combi sensors

Should a sensor cell require to be replaced, the sensor should have its power removed before changing the cell itself. Flammable (Catalytic) and Toxic cells have colour coded wiring which is Pink, Yellow and White which should be connected correctly according to the markings on the PCB. Fig 5 on page 43 and data sheets C893 & C894 at the end of this document detail the procedure for setting up a new sensor independent of the Combi panel and then when connected to Combi follow the above zero and span procedure.

Setting the Time to Alarm

Using **ENGINEER•S** menu 26, the time in seconds required to detect a direct 4-20 alarm can be set to a maximum value of 60 seconds. This is useful in certain installations where transient gas presence is allowed and gas detection alarms quickly become a nuisance.

The **UP (1)** and **DOWN (5)** buttons change the channel and the **+** **(4)** and **...** **(2)** buttons will alter the time in increments of 1 second.

Pressing **SELECT (3)** will present the same choice for the addressable channels.

Pressing **SELECT (3)** again returns to the **ENGINEER•S** menu after saving these times.

Setting Alarm levels

The high and low alarm points for the sensors can be set manually using **ENGINEER'S** menu 21 for direct 4-20 alarm levels and menu 15 for addressable alarm levels.

Menu 15 for addressable sensors

Use **UP (1)** and **DOWN (5)**, to choose a sensor which requires an alarm change.

Use **+** **(4)** and **...** **(2)** to adjust the low alarm point.

Pressing **SELECT (3)** will then request you to set the High alarm point.

Pressing **SELECT (3)** again allows the Over Range alarm to be set.

Use the **RESET** button **(7)** to select **RISING** and **FALLING** alarm.

Pressing **SELECT (3)** again will exit the menu and save the parameters to memory.

Setting Number of Decimal Places (18)

Using **ENGINEER•S** menu 18, the number of decimal places displayed by the **•Gas Value•** can be set to 1 or 2. This is global command for direct sensors only. For addressable sensors the decimal places selection must be set individually at the sensor via PC hyper-terminal, (see Combi sensor datasheets C893 & C894).

The **RESET (7)** button changes this menu from the **•Alter Gas Type•** screen to the **•Change Range•** screen. On the Change Range screen use **RESET (7)** to switch between **•DP=1•** and **•DP=2•**. This toggles the displayed Gas Value between 1 and 2 decimal places respectively.

Press **SELECT (3)** to return to the **ENGINEER•S** menu.

Setting the 4~20mA Deadband (18)

Using **ENGINEER•S** menu 18, the 4~20mA deadband can be switched ON or OFF.

This is a global command for direct sensors only. For addressable sensors this must be set individually at the sensor via PC hyper-terminal, (see Combi sensor datasheets C893 & C894). The **RESET (7)** button changes this menu from **•Alter Gas Type•** screen to the **•Change Range•** screen.

Alarm relay off timers

The 8 relays on the PCB are allowed to take time to de-energise.

For example, this delay could be used to keep fans running for a longer period after the gas alarm to allow a larger area to be vented.

ENGINEER•S menu 24 allows each of the 8 relays to be selected by using the **UP (1)** and **DOWN (5)** buttons and then for each relay use the **+** **(4)** and **...** **(2)** buttons to change the time for delay in increments of 1 second. The minimum time is 1 second.

Additionally, the first 16 external relays can also have a time delay to de-energise which has been output by an event or pattern.

Pressing **SELECT (3)** will save the delay times in non volatile memory and return to the **ENGINEER•S** menu.

Voting relays

(Note: 4 of these relays are also used with time weighted alarms)

ENGINEERING menu 25 allows channels to be assigned to a group voting system.

8 relays on the main PCB will be activated according to the voting set up, and de-activated when the condition has subsided and after the relay off timer has expired.

Using **UP (1)** and **DOWN (5)** to select the group, then use the **+** **(4)** and **...** **(2)** to select how many alarms have to be active in this group to cause a relay to activate.

E.g. group 2 may have 5 sensors in its group and 3 alarms are required to activate relay called High (G2).

On entering menu 25, the direct 4-20 channels are displayed. **UP (1)** and **DOWN (5)** buttons will display which groups this channel is in whilst the **+** **(4)** and **...** **(2)** buttons change the channel being viewed. If a channel was in groups 1 and 3 then the display would be 1-3-----. If it was in groups 2, 3 and 7 then the display would be -23---7-.

Pressing **UP (1)** or **DOWN (5)** changes this selection so keep pressing until the correct grouping for your application appears. Any channel can be in all groups and this would be displayed as 12345678.

Pressing **SELECT (3)** presents the Addressable channels for a repeat of the above.

Groups can contain a mix of sensors from 4-20 direct or Addressable channels.

Time weighted alarms

(Note: This applies to OPT5,6,7,8 relays)

Two types of time weighted alarms can be set using menu 31. STEL is a short time exposure level which is a weighted average of gas level for the last 15 minutes. It is associated with one of the four groups (5,6,7,8) of sensors. Each group may have any number of sensors within it and whichever is the highest reading in the group, this reading is used to formulate the value of STEL.

LTEL is a long time exposure level taken over 8 hours and calculated in the same way as STEL. Both STEL and LTEL have individual alarm settings but both act upon the same relay. These alarms are rising only. Each gas must clearly be of the same type. If STEL or LTEL alarm level is set to a value greater than zero, then this voting group becomes a TWA (Time Weighted Average) group and the normal voting function is suppressed.

Defaulting the panel

Individual sections of the panel can be defaulted rather than restoring all the defaults within the panel. This is useful when one particular section of retained data needs to be reset. See **ENGINEER•S** menu 32 for details.

Default the whole panel from power up

At manufacture of a new processor board and possibly in service if a new set up is to be installed, it is necessary to clear all system parameters and load default settings. This can be done by pressing and releasing the processor reset button on the PCB at the same time that the **SELECT (3)** button is pressed and held down. Release the **SELECT (3)** button when the LCD displays the message •Initialising NVRAMŽ.

Clearly, this is only to be done if you are sure that a complete default is required. Always ensure that a copy of the old set up is available in a text file which could be reloaded if needed.

Repeater (on CAN2 only)

It may be required to have a duplicate console sited elsewhere, such as a control room or instrument room.

Using the CAN network, 4 core (2 data + 2 supply) cable, a repeater can be connected which gives a user interface identical to the main Combi panel. In fact the data displayed on the repeater board is transmitted from the main panel.

Likewise, button pushes on the repeater are transmitted to the main panel and are used by the main panel as if they had been pressed locally.

To ensure the correct operation of the repeater, it has to be set up in order to accept CAN from a main panel and also to know where to send its own CAN data. It is a requirement that the CAN2 bus is used for repeaters leaving CAN1 for sensors and other devices.

Sensors are able to use CAN2 at the same time as a repeater providing that the addresses are different.

From power up or by pressing the processor reset button on the repeater and pressing the **SELECT (3)** button at the same time the following sequence will occur on the LCD after releasing the select button.

Set THIS ADDRESS using the **UP (1)** and **DOWN (5)** buttons to choose a free address that the repeater will use as its own address. Note this has to be different from that of the main panel (which defaults to address 201)

Press **SELECT (3)**

Set FROM ADDRESS, this is the address of the main panel which will send LCD and LED data out to this repeater to be displayed.

Press **SELECT (3)**, the two addresses will be stored.

The repeater is now awaiting data from the FROM ADDRESS and it will display an error if the panel does not receive data for 30 seconds.

To initialise communication between the Combi main panel and the Repeater panel return to the main panel unit and follow the instructions in the Set Up Network section of this manual (p.14).

Installation

SITING THE SENSING HEADS

A key feature of the installation is the correct positioning of the sensor. Several considerations must be taken into account, the most important being the density of the gas.

| Density (air = 1) | | | |
|-------------------|------|-------------------|---------|
| Acetone | 2.0 | Hydrogen-Sulphide | 1.18 |
| Acetylene | 0.91 | Hydrogen | 0.069 |
| Ammonia | 0.6 | Methane | 0.6 |
| Benzene | 2.8 | n-Pentane | 2.5 |
| n-Butane | 2.0 | n-Propane | 1.6 |
| Carbon Dioxide | 1.53 | Town gas | 0.4-0.7 |
| Carbon Monoxide | 0.96 | Xylene | 3.7 |

Under still air conditions, a lighter than air gas such as methane leaking from a small aperture at ground level, will rise in a plume the shape of which approximates an inverted cone. As the gas rises, it draws air from the surroundings and creates turbulence. Due to this rapid dilution of the gas occurs and, unless a sensor is positioned within the plume, there will be no initial indication of a leak.

As gas continues to escape, the diluted methane rises to ceiling level and begins to layer.

In time the concentration at ceiling level will increase and this, in turn will displace air downwards.

Dangerous concentrations will therefore, tend to occur at ceiling level and the thickness of this layer will increase with the passage of time.

Ventilation of the room will of course alter the situation significantly but it should be remembered that if the ventilator is not at ceiling level, a dangerous concentration can still occur between the top of the ventilator and the ceiling.

For heavier than air gases such as propane or butane, the formation of dangerous layer occurs at ground level. These gases tend to behave like water and will run down gradients and pool at the lowest point.

The number of heads required in individual rooms is determined by the number of possible hazards in the vicinity.

Gas leakages may occur around valves, flanges and wherever gas pipes are jointed. It may be possible to cover several probable gas leaks in one room by the careful siting of a single head. Cable ducts, trenches and manholes are also likely places where a build up of heavy gases may occur.

When siting a head in such places it is important to ensure that there is no likelihood of flooding by water, or excessive dust which may block the sintered disc and prevent gas from reaching the sensor.

When monitoring gases outside, those lighter than air will be quickly dispersed, but gases heavier than air will tend to form in layers and again cause a dangerous hazard. When siting heads outdoors prevailing winds must be taken into consideration and adequate protection given against wind and rain by the use of weather or collector cones.

The control unit is designed for installation in a safe area only. Positioning of the instruments should be chosen with regard to the following points:

- € Away from sources of local heat with room for adequate ventilation
- € Within easy reach and audible distance of operating personnel
- € Convenient to a separately fused power supply
- € Incoming sensor cables and outgoing alarm annunciation
- € Sensor cables to be electrically shielded, steel wire armoured or screened cable
- € Sensor cables to be run separately from power cables.

Mains operated Units

- € The equipment should be supplied from a 2A fused/switched spur.
- € The spur unit should be identified and positioned locally to the equipment.
- € To prevent lateral cable movement the mains cable within the enclosure should be restrained using a clamp.
- € Earth leads within the enclosure should be a minimum of 300mm longer than the mains Live and Neutral cores

Field cables which are terminated within the control unit enclosure should be kept as short as possible and not allowed to cross over electronic components or the ribbon cable. See Figures 2, 3 and 5 for connection details.

To prevent any effect from earth currents the cable shielding should be grounded at the equipment end only.

The instrumentation should be subjected to a minimum of vibration and shock.

Ascertain the voltage rating of the power supply to which the instrument will be connected

The Type of cable which should be used is:

| | | |
|----------------------|--------------|----------------|
| Addressable CAN bus: | 4 core, | 1.5mm screened |
| Direct: | 2 or 3 core, | 0.5mm screened |

DO NOT POWER UP THE INSTALLATION PRIOR TO COMMISSIONING BY OUR ENGINEERING STAFF.

Combi Sensor Cable Routing

Addressable Sensors:-

Two sets of four way terminals for each of the two CAN channels, CAN1 and CAN2, are available for connection of addressable sensors and auxiliary equipment to the control panel. Connection of sensors to the control panel requires a 4 core 1.5 mm (minimum) screened cable, two of which supply the 24Vdc sensor supply with the remaining two used for the CAN communication between the sensors and control panel.

The addressable sensors should be connected to the two CAN channels in such a way that, the total numbers of end of line links does not exceed three on each of the two CAN channels. Spurs of four metres or less do not require an end of line link. The end of line link must be positioned on the very last sensor on each sensor cable run from the Combi.

Direct Sensors:-

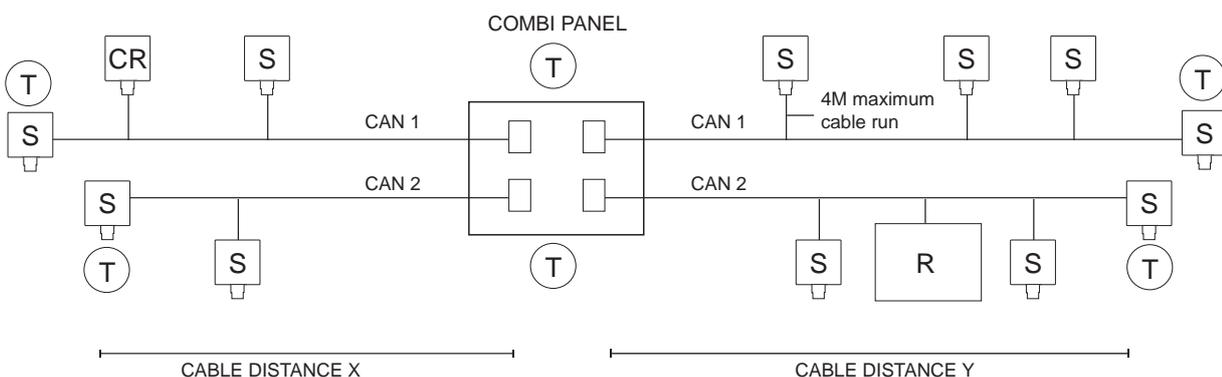
Sixteen direct sensor inputs, each with three terminals, are available for terminating the two or three wire sensors (4-20mA devices) to the Combi. The sensors connected to these direct inputs must operate in source mode only. Combi panel will not work with sensors operating in sink mode.

Repeaters:-

Repeaters should be connected to CAN2 channel only.

Network Controllers:-

In networking mode the sensors must only be connected to CAN1 channel. CAN2 channel is used for networking the system only.



Maximum cable distance for CAN signal $X+Y = 1\text{km}$

Maximum distance for sensor voltage drop - minimum sensor operating voltage 17Vdc

- R = Repeater Panel
- S = Sensors
- CR = CAN Relay
- T = Fit terminator link on PCB

Equipment Installation Guidelines

Standards

Follow the correct electrical installation procedure and legislation (IEEE Regs)

Junction Boxes

- DO check area classification for junction box suitability
- DO use boxes appropriate to the environment
- DO ensure correct IP rating for the environment
- DO use adequate sizes of field junction boxes
- DO allow for spare ways and future expansion
- DO mount field junction boxes at working height
- DO remember that water can't get OUT of weatherproof boxes once it is inside!
- DO employ a weather resistant tag to identify the equipment
- DO prevent water/product ingress through the cables/glands ... enter box from side or bottom
- DO plug all unused ports with appropriate stoppers
- DO clean out the junction box after installation

Cables

- DO check area classification for cable type
- DO ensure cable runs and distances to sensors are as recommended by the manufacturer of the equipment
- DO document and record all cable routes
- DO use the correct size and type of cable for the application ... screened cable for instrumentation
- DO keep signal cables away from power cables
- DO ensure that loop resistance values are not excessive
- DO ensure that the cable is of suitable quality for its intended environment
- DO avoid major sources of electrical interference when planning cable runs, away from motors etc.
- DON•T exceed maximum cable parameters for IS systems
- DON•T run the cable over sharp edges or around overly tight bends
- DON•T overstress cable support cleats/ties

Glanding

- DO check area classification for gland type
- DO get it right first time. It is very difficult to correct it later
- DO use the right type of gland for the application
- DO leave generous service loops in the sensor cables
- DO fit a sealing washer if required for weatherproofing
- DO ensure that any RFI shield is properly isolated from safety earth metalwork and gland body
- DO ensure that the SWA earthing is continuous and vibration proof
- DO ensure that the cable sheath makes a weatherproof seal
- DO fully tighten all fittings
- DON•T use tape for weatherproofing
- DON•T hide bad workmanship under shrouds

Terminations

- DO terminate cables to the correct points to prevent damage to the system
- DO sleeve and terminate earth wires correctly
- DO remain consistent in the allocation of wire colours
- DO remember to attach cable and termination markers to aid maintenance
- DO ensure that cable insulation extends right up to the throat of the terminal
- DO ensure that there are no bare wires or wire strands
- DO use the correct tool for crimp connections
- DO pull test every one before termination
- DO use the correct width terminal screwdriver to avoid cracking terminal blocks
- DO ensure that terminal screws are adequately tight

Earthing

- DO maintain separation of Safety, Instrument and IS Earths
- DO ensure that earth continuity is maintained through field junction boxes
- DO ensure that metallic outer enclosures are adequately earthed for safety
- DO allow for any IS Barriers in systems with earth fault monitoring

RFI Screening

- DO use suitably screened instrument cable for sensor runs
- DO maintain separation of safety earths and screening
- DO connect screening as advised by equipment manufacturers
- DO ensure continuity through junction boxes/equipment housings

Lightning

- DO keep instrument cables away from susceptible power and earth cables
- DO fit surge protectors in areas subject to severe electric storms

Equipment

- DON•T power up until commissioning
- DO check area classification for equipment suitability
- DO ensure correct IP rating for the environment
- DO check power requirements
- DO power from a separate fused spur (AC)
- DO locate away from sources of heat
- DO mount gas sensors in accessible locations, at the correct height
- DO note position of end of line addressable sensor
- DO mount at accessible working height for ease of commissioning and maintenance
- DO protect the equipment from paint/steam and other contaminants
- DO ensure easy access to the interior of the equipment
- DO mount within easy reach and audible distance of operating personnel
- DO protect from vibration
- DO employ a combination sun and rain shield in all outdoor locations
- DO power from a clean adequately rated AC/DC supply (no inverters fed from the same supply)
- DO run cable within equipment enclosure away from components and circuit boards
- DO keep cables within the equipment enclosure as short as possible
- DO keep operating manuals adjacent to the equipment

Testing

DO complete the cable installation testing BEFORE final termination at either end

DO record the cable loop resistance values to aid troubleshooting later

Documentation

DO record cable routing and equipment/junction box locations

DO track all changes by updating the system documentation

DO keep records adjacent to the equipment

Service ... routine attention

The owner or occupier of the premises should place the supervision of the system in the charge of a responsible executive, whose duty it should be to ensure the day to day operation of the system and to lay down the procedure for dealing with a gas alarm, (see below) or fault warning. To ensure reliability an agreement should be negotiated for regular servicing. When a service contract cannot be arranged an employee with suitable experience of electrical equipment should be trained to deal with the simpler servicing and instructed not to attempt to exceed the scope of such training.

Liaison should be established with those responsible for maintenance of the building fabric or redecoration etc. to ensure that their work does not cause a fault or otherwise interfere with the operation of the alarm installation. Particular attention should be paid to the Detector Head.

The operating instructions should be kept available with the control unit; all faults, service tests and routine attention given should be recorded.

DAILY

A check should be made that any fault condition which may be indicated is in fact being attended to and that all other indicators are normal.

TWICE YEARLY MAINTENANCE SCHEDULE

1. All zeros at the control unit to be checked logged and aligned.
2. Each detector to be gas tested and reading logged (sensitivity checked).
3. Field indicators to be tested.
4. All alarm set points checked and re-aligned.
5. Lamp Test.
6. All faulty parts replaced where required.
7. All filter elements checked and replaced as necessary.
8. Power supply ... complete functional check.
9. Visual inspection made to confirm that all cabling fitting and equipment is secure, undamaged and adequately protected.

ACTION TO BE TAKEN IF THE APPARATUS ALARM SOUNDS:-

- A. Extinguish all naked flames, including smoking materials.
- B. Turn off all gas appliances.
- C. Do not switch on or off any electrical lights or appliances.
- D. Turn off the gas supply at the gas emergency control and/or (with L.P.G supply) the storage tank.
- E. Open doors and windows to increase ventilation.

If the alarm continues to operate, even after an alarm re-setting action where appropriate, and the cause of the leak is not apparent and/or cannot be corrected, vacate the premises and immediately notify the maintenance engineers / safety officers / emergency services or gas supplier and/or the gas emergency 24 hour service in order that the installation may be tested and repair work carried out in order to make the installation safe.

Appendix 1

Menu details by number

1] View Modbus Reg

This allows inspection of the 250 internal Modbus registers. Use **UP (1)** and **DOWN (5)** buttons to alter the register which is displayed in Decimal and Hexadecimal. **SELECT (3)** button will exit.

2] Set Clock

Using **UP (1)** / **DOWN (5)** and **SELECT (3)** allows the date and time to be changed.

Note, if the CAN communication connection is made to other Combi panels, the time from the lowest address panel will impose itself onto higher panels. So this means that the time should only be adjusted on the lowest address panel and then this new time will appear on other higher address panels.

3] Inhibit all Sensors

Using **UP (1)** and **DOWN (5)** buttons, the direct or addressable sensors can be inhibited.

4] View Modbus TXRX

As a diagnostic tool for Modbus communications, this display shows the data packets received from a Modbus master (RX) and the reply sent back from the COMBI panel (TX)

This display is in Hexadecimal and to understand the meaning, the Modbus data packet protocol has to be analysed. This menu is generally used when first getting the Modbus system running. Use **SELECT (3)** to exit this menu.

5] Set Refresh Rate

Use **+** (4) and **...** (2) to change the display refresh rate for sensor data on lines 1 and 2 of the LCD. 1 is fastest and 10 is slowest. Pressing **SELECT (3)** will exit this menu.

6] Edit Company Text

The fourth line of the LED display alternates between time and company text. This text can be edited to show the site or installer details.

7] Lamp Test

This menu will illuminate all front panel LED's on the main PCB and those on the remote LED board when connected.

When complete, the PCB buzzer will sound and the menu exits.

Note that the LED test is done with DIM active to save excessive current from the PSU.

8] Relay Test

The local group of 8 relays can be energised or de-energised using **+** (4) and **...** (2) Pressing **SELECT (3)** allows the 64 (2x32) relay card to be tested. Press **UP (1)** and **DOWN (5)** to choose which of the 64 relays to test and the **+** (4) button will energise it. The **...** (2) button will de-energise the relay. The state of the relay can be seen via individual LEDs on this board. **SELECT (3)** will exit the menu.

9] Event Log to LCD

The internal 99 event log can be viewed on the LCD display one event at a time.

Each line of the display indicates the following

Line 1 shows the type of event with the time of occurrence.

| | | |
|-----------|---------|---|
| Types are | FLT | is a fault such as sensor 1 fail |
| | Hi Alrm | is high alarm |
| | Lo Alrm | is low alarm |
| | SYS | is a system event such as a panel reset |

Line 2 and 3 show text relating to the event.

Line 4 shows which event is being displayed and how many events are logged.

e.g. 3 of 76 events means that the display is showing event 3 and 76 events are logged.

76 is the oldest event and 1 is the latest event.

Use **UP (1)** and **DOWN (5)** to choose which event to view.

SELECT (3) will exit the menu.

10] Addressable Zero and Span

The first part of this menu allows you to zero an addressable CAN channel.

The channel is selected by using **UP (1)** and **DOWN (5)** buttons and the reading itself is adjusted by pressing **+** **(4)** and **...** **(2)**.

This menu will timeout and the number of seconds left is displayed on the LCD.

SELECT (3) will exit the zero menu and present the span menu.

The channel is selected by using **UP (1)** and **DOWN (5)** buttons and the reading itself which is based on the peak readings is adjusted by pressing **+** **(4)** and **...** **(2)**.

This menu will timeout and the number of seconds left is displayed on the LCD.

Because peak readings are used, a number of sensors can be spanned at the same time.

11] Set LCD backlight and LED Dimmer

The value of brightness for the LCD/LEDs when dimmed is set using **UP (1)** and **DOWN (5)**

buttons, **SELECT (3)** will exit the menu. The actual brightness is displayed on the LCD as a percentage and on the front panel LEDs themselves whilst adjusting. This level of brightness will be used in normal mode when the DIM button is pressed.

12] Is an Exit Point

13] Is top of the Engineer's Menu

14] Inhibit a Sensor

During maintenance, individual sensors can be inhibited so that false alarms are not indicated.

A front panel LED illuminates to indicate that at least one sensor has been inhibited in the

system. The first part of this menu allows a direct sensor to be inhibited using the **+** **(4)** and **...** **(2)**

to toggle the state. The LCD indicates whether inhibited or not and the **UP (1)** and **DOWN (5)**

buttons change the channel. Note that only channels with active sensors can be inhibited.

Pressing **SELECT (3)** or timeout will move to the second part of this menu which allows addressable CAN sensors to be inhibited in the same way.

Pressing **SELECT (3)** will exit this menu.

15] Addressable Alarm Levels

The alarm levels for can sensors can be changed in this menu

Three levels are presented, LOW, HIGH and OVER RANGE

Use **+** **(4)** and **...** **(2)** to change the LOW level and the **UP (1)** and **DOWN (5)** buttons which alter the channel being changed

Pressing **SELECT (3)** moves to HIGH alarm

Pressing **SELECT (3)** moves to OVERANGE

Pressing **SELECT (3)** exits this menu.

16] Clear All Addresses

This menu option is used to clear currently unsued addresses that were previously connected to CAN devices without having to power off or reset the control unit.

This is beneficial if devices such as warning alarms are connected to •normally closed• relays.

17] Alter Channel Text

Each sensor has text associated with it to describe its location.

This text can be altered manually if required using this menu.

Use **UP (1)** and **DOWN (5)** to choose the line to be edited and then press **+** **(4)** to go into edit

mode. A small cursor will appear below the text indicating that the character above it can be

altered. Use **+** **(4)** and **...** **(2)** to change the character and use **UP (1)** and **DOWN (5)** to move the cursor to another character position.

SELECT (3) will complete the editing and return to choose another line.

SELECT (3) again at this point will exit the menu.

Note: Using PC to PANEL allows this text to be loaded from a PC which is much quicker.

18] Alter Gas Type and Range

The gas type, default range, number of decimal places and deadband can be selected using this menu. Use **UP (1)** and **DOWN (5)** to choose the channel, and **+** **(4)** and **...** **(2)** to change the gas type. Press **RESET (7)** to change range using **+** **(4)** and **...** **(2)**. Press **RESET (7)** to toggle between 1 and 2 decimal places. Press **DIM (6)** to toggle the deadband on and off. Press **SELECT (3)** to exit this menu.

19] View Addressable Sensor Data

This menu allows the viewing of data received from an individual CAN sensor for upto 24 hours. Use the **UP (1)** and **DOWN (5)** buttons to choose the sensor channel to be displayed. The data displayed is as follows:

| | | |
|---------|------------------|-----------|
| Addr 00 | Timeout in 00sec | Lowest=00 |
| ST1 00 | ST2 00 | Rstat 00 |

Pressing **SELECT (3)** again exits this menu.

20] Adjust 4~20mA Zero and Span

Normally a gas sensor will be calibrated as a separate item but minor adjustments to the readings of any of the 4~20 sensors can be made at the panel using this menu. Use **UP (1)** and **DOWN (5)** initially to choose the gas sensor to be calibrated. Then press **SELECT (3)** and use **UP (1)** and **DOWN (5)** to alter the maximum value of the sensor if required. Then press **SELECT (3)** to start adjusting the zero for this sensor (with no gas present). **UP (1)** and **DOWN (5)** make minor adjustments and when reading of zero is achieved press **SELECT (3)** to move to a span adjustment (apply span gas). **UP (1)** and **DOWN (5)** will adjust the internal gain to make the reading correct according to the span gas applied.

Press **SELECT (3)** to exit this menu.

21] Set 4-20 direct Alarm Levels

Alarms occur when the gas values for each sensor are above or below these alarm levels (Oxygen can be below) and the level can be adjusted using this menu.

Use **+** **(4)** and **...** **(2)** to select the sensor channel to be adjusted. Pressing **RESET (7)** will toggle between rising and falling alarms.

Adjustment of the LOW alarm is done using the **UP (1)** and **DOWN (5)** buttons

Pressing **SELECT (3)** again allows adjustment of the HIGH alarm using the same buttons

Pressing **SELECT (3)** again allows adjustment of the OVER RANGE alarm using the same buttons

Pressing **SELECT (3)** again will exit the menu.

22] Unlatched Alarms

Each sensor channel can have latched or unlatched alarms. This menu shows the current state of this feature and can be toggled by pressing **+** **(4)** or **...** **(2)**. The sensor channel is selected by using the **UP (1)** and **DOWN (5)** buttons. Unlatching alarms will clear automatically when the gas level is below the alarm point. Pressing **SELECT (3)** will exit this menu.

23] Event to relay 64

Each event which is stored in the 99 event log can also activate a relay. Use this menu to choose which relay. Use **UP (1)** and **DOWN (5)** to choose the event (which is displayed on the LCD) and then use **+** (4) and **...** (2) to choose which of the 64 relays to drive. The default is not to drive any relays.

Also, each event can drive the first 16 relays as a pattern which is ORed in. This means that patterns which overlap will mix together and effectively create a group action. Each event has its own individual pattern of 16 bits, where 1 = relay active and these can be edited using the display where a cursor is moved using **+** (4) and **...** (2) buttons and **UP (1)** and **DOWN (5)** will set one and zero in the cursor position.

gfedcba987654321 represent the 16 relays. 1 = relay 1 and g = relay 16.

With so many events needing patterns, it is usual to download these patterns from a PC using menu number 29. Note: that if a relay is normally energised (menu 36) then the effect of a 1 will turn the relay off. Pressing **SELECT (3)** will exit this menu.

Additionally, pattern 8765 321 can be redirected to 7 relays on the Combi input PCB. The fault relay 4 always remains as Fault but the remaining relays are assigned as follows:

Low, High, Overange, Opt1, Opt2, Opt3, Opt4. These will mimic remote relays 123 5678 respectively. This feature eliminates the need to fit a remote relay PCB for smaller installations. Pressing **SELECT (3)** will exit this menu.

24] Relay off Timers

Each of the 8 relays on the main PCB can have delayed de-energise times and this menu allows you to set the delay in seconds. Use **UP (1)** and **DOWN (5)** to select which of the 8 relays to set and then **+** (4) and **...** (2) to alter the time. The minimum time is 1 second and the maximum is 255 seconds. This feature is extended to the first 16 relays which have a pattern output created by an event. **SELECT (3)** will exit this menu.

25] Channel Voting

There are 4 groups of sensors which drive 4 option (voting) relays. This menu allows you to set how many alarms in a group are required before its relay will energise and then which sensors are in the group. Sensors can be in any group or multiple groups or no groups.

The first part of this menu enables you to set the number of alarms by using **+** (4) and **...** (2) buttons. The maximum is 10 alarms. Use the **UP (1)** and **DOWN (5)** buttons to change the group number being set. Pressing **SELECT (3)** goes to the second part of this menu this sets which group the 4-20 direct channels are in followed by the addressable channels. The **+** (4) and **...** (2) changes the group and **UP (1)** and **DOWN (5)** changes the channel.

| | |
|--|-----------------|
| If a sensor channel is in group 1 the display would be | 1 - - - - - |
| If a sensor channel is in group 3 the display would be | - - 3 - - - - |
| If a sensor channel is in group 1 and 3 the display would be | 1 - 3 - - - - |
| If a sensor channel is in group 1, 2, 3 and 7 the display would be | 1 2 3 - - - 7 - |
| If a sensor channel is in no groups the display would be | - - - - - |

Pressing **SELECT (3)** will exit this menu.

26] Seconds to Alarm

When an alarm condition exists it is possible to delay the response and if the alarm still exists at the end of this delay then a normal alarm condition is recognised. This menu allows you to set this delay to a maximum of 60 seconds. For 4-20 direct sensors first use **UP (1)** and **DOWN (5)** to change the channel and **+** (4) and **...** (2) to alter the time in seconds. Pressing **SELECT (3)** presents the same choice for the addressable sensors. Pressing **SELECT (3)** again will exit this menu.

27] Setup Network

Both Modbus and CANbus require that this panel has a communication address and this can be set using this menu. **UP (1)** and **DOWN (5)** change the displayed address which is common to both CAN1 bus and CAN2 bus. Pressing **SELECT (3)** changes the display to view of all CANbus devices currently connected to this panel. The purpose of this is to find an address which has a repeater panel and then to decide if this panel should be connected to it. The address is displayed together with the type of device seen. A ? is displayed if nothing is present at the displayed address. The letter P would appear if another panel was seen. The letter R would appear for a repeater and The Y/N letter states whether this panel is currently connected to it, **+** (4) toggles this connection. Once connected the buttons, LED•s and LCD on the main panel and the repeater match in operation and display. The letter S would appear if a relay / sounder device is found. The letter C will appear for a CAN sensor. Pressing **SELECT (3)** will exit this menu.

Changing the address of devices on the CAN network

If a •C• is detected an additional function is displayed. By pressing the RESET (7) button, the address can be changed to a new value using the + (4) and ... (2) button but only if an address link has been inserted. This link should be removed afterwards.

Note: If more than 1 device has a link inserted then all these will have their address change to the new one and will give rise to a duplicate error which must be resolved. It may be required to use menu 16 which clears all unused sensor addresses from the panel (such as after disconnecting a sensor to allow that address to be available).

28] Event log to PC

It is possible to send the event log to a PC for storage etc. Using HyperTerminal on the PC set to 2400 baud, 8bit, no parity, no flow control. The events are sent one by one in ASCII characters to the PC using the RS232 connection. The HyperTerminal can be set to capture text and then save it. The file sent is text only and can be printed or edited as required. This menu will exit automatically when all data is sent.

29] Data PC to Panel

To get data from a PC to this panel to set up Text, Gases, Alarms, etc this menu prompts you to set up HyperTerminal on your PC and then waits for data to be sent in a prescribed format ending in •:XŽ. When the text has been sent, any valid data is stored. Bad data and comments are ignored. Valid command letters only are echoed to the PC screen. This menu will drop out if data is not sent in 60 seconds and also can be aborted by pressing SELECT (3).

30] Data Panel to PC

The panel may already have Text, Gas and Alarm data stored and you may wish to have a copy held on the PC for future backup. This menu allows you to send this data and the PC will receive it in HyperTerminal using the Capture text function. When saved on the PC, this text can then be edited using a simple text editor (such as Notepad) and then sent back to the panel if required. Pressing SELECT (3) starts sending the data to the PC and when finished, this menu will exit automatically.

31] LTEL, STEL Alarms

This menu allows you to set the time weighted average alarms for groups 5, 6, 7 and 8.

32] Default Sections

Sometimes it is required to default part of the data in the panel and this menu allows you to do this. (Some options are repeats of other menus) Pressing **SELECT (3)** moves to the next option and pressing **+ (4)** defaults the option displayed.

The options are:-

| | |
|--------------------------|---|
| Clear event log | Clears all events in the 99 event log |
| Default Modbus/Canbus | Defaults baud rate to 9600 and address 1 |
| Default gas type to Flam | All sensors become FLAM type |
| Default Line text | Defaults to 4-20 text or CAN text |
| Default event to relay | All events do not drive any of the 64 remote relays |

33] Change Engineer's Password

The engineer's password can be changed from this menu. you will be prompted to enter a new code twice via the buttons. Pressing **SELECT (3)** will exit this menu.

Note: The user password cannot be changed.

34] Set Modbus Baud

This menu allows you to change the Baud rate used by the Modbus (default is 9600). The options are 19200, 9600, 4800 bits per second and these are altered using the UP (1) and DOWN (5) buttons, Pressing **SELECT (3)** will exit from this menu.

35] Set Power Alarms

The panel detects both mains power and battery/DC power. When only one power source is in use it is convenient to disable the loss detection of the other source so that the panel is not in continuous fault. This menu allows you to inhibit the battery alarm first and by pressing **SELECT (3)** then the mains alarm. The **+ (4)** and **... (2)** buttons toggle whether or not each alarm is inhibited, this is displayed on the LCD. Pressing **SELECT (3)** will exit this menu.

36] Set Energised Relays

This menu allows relays to be set as normally energised (=1) or de-energised (=0). 8765FOHL represents the 8 on board relays

gfdcba987654321 represents the first 16 external relays

Using **+ (4)** and **... (2)** buttons, the small cursor moves along a pattern of ones and zeros which represent the normally de-energised or energised setting and this can be changed using the **UP (1)** and **DOWN (5)** buttons.

Press **SELECT (3)** to exit this menu.

Appendix 2

Below is an example of a typical text file that can be sent to/from the COMBI system.

PLEASE NOTE:

- 1) • : • = Direct Sensor, • * Ž = Addressable Sensor
 - 2) Lines of the same command but different addresses have been deleted
 - 3) The difference between patterns and groups is that there are 16 patterns, and 8 groups.
 - Groups can only be used to control a single relay per event.
 - Should the user require two or more relays to be activated by a single event, patterns MUST be used.
 - Patterns primarily output to the first 16 relays on the 32 way relay card.
 - We then tell the control unit to mimic 7 of these relays by
 - € going into option #23 (*event to relay 64)
 - € Pressing •select• 12 times so that •L,H,O,F,o1, o2, o3, o4Ž is displayed
 - € Exiting
- The Control unit is now setup to mimic 7 relays of the 32 way relay PCB

| Combi Text File Command (Summarised) | Description |
|---|--|
| Data to PC from panel address 1 :=4-20 and *=Addr Note letters after : and * are case sensitive. :c, | Start of text file |
| NAME OF COMPANY Tel: # # # # # # | Any text can be put here up to 40 characters |
| :Seconds to alarm 1, 30, | (x16) ... the period of time that the sensor must detect the gas before it activates the control unit alarm |
| *Seconds to alarm 1, 5, | (x64) - the period of time that the sensor must detect the gas before it activates the control unit alarm |
| :Alarmdir LHO 1,RRR | (x16) ... Alarm direction (Lo / Hi / OR). R=Rising, F=Falling |
| *Alarmdir LHO 1,RRR | (x64) - Alarm direction (Lo / Hi / OR). R=Rising, F=Falling |
| :a1,1 :a2,1 :a3,1 :a4,1 :a5,1 :a6,2 :a7,1 :a8,1 | •Group• setup. a1, a2 etc.. is the relay reference. It determines how many alarms there needs to be before each group relay activates Example: Group #6 need two sensors to be in alarm for relay activates |
| Group87654321 :g01,00000001 | Direct channel #1 is in group 1 |
| Group87654321 *g01,00001001 | CAN channel #1 is in group 1 also, and in group 4 |
| :T1,LEL.SENSOR.1....., *T1,O2.SENSOR.1....., *T2,boiler roomff., | (x16) ...Text for direct sensors connected. (E.g. this could represent the location of the sensor: - i.e. boiler house, pump room etc.) (x64) - List of addressable sensors connected. You can also set the name of the sensor: (ie boilerhouse, pump room etc.) |
| :G1,%LeL , | (x16) ... Direct Gas type |
| :unlatchedAlarm 1 | (x16) Direct alarms ... •latchedalarm #• or •unlatchedalarm #• |
| *unlatchedAlarm 1 | (x64) Addressable alarms ... •latchedalarm #• or •unlatchedalarm #• |
| :LoDirAlarm 1 ,200, | (x16) Direct •Low• alarm level. Note: values are 1 significant figure ... e.g •200• = •20.0• ... (using list of direct sensors connected) |
| :HiDirAlarm 1 ,400, | (x16) Direct •High• alarm level. Note: values are 1 significant figure ... e.g •400• = •40.0• |
| :OrDirAlarm 1 ,999, | (x16) Direct •Overrange• alarm level. Note: values are 1 significant figure ... e.g •999• = •99.9• |
| *LoCanAlarm 1 ,190, | (x64) Addressable •Low• alarm level. Note: values are 1 significant figure ... e.g •190• = •19.0• (Oxygen would be •FFR•) |
| *HiCanAlarm 1 ,170, | (x64) Addressable •High• alarm level. Note: values are 1 significant figure ... e.g •170• = •17.0• |
| *OrCanAlarm 1 ,250, | (x64) Addressable •High• alarm level. Note: values are 1 significant figure ... e.g •250• = •25.0• |
| Event to Relay (Note keep in correct sequence) Direct Chan 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 :Fault 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, :first alarm 4, 5, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, :second alarm 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, :third alarm 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, | Each event can drive 1 relay of the 64 external relay card. Determines which relays activate for each direct channel on each of the 4 alarm types In this example, relay 4 will trigger if direct chan 1 goes into •Lo• alarm, and relay 5 will trigger for channel 2 Note this is where Voting can be introduced (described above) Note: no same relay can be used for two events |
| Address Chan 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 *Fault 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, *first alarm 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, *second alarm 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, *third alarm , 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, | See above ... but for addressable sensors 1-16 |
| Address Chan 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 *Fault 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, *first alarm 6, 6, 6, 6, 6, 6, 6, 6, 6, 6, 6, 6, 6, 6, 6, 6, *second alarm 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, *third alarm 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, | See above ... but for addressable sensors 17-32 |

| | |
|---|--|
| <pre> Address Chan 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 *Fault 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, *first alm 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, *second alm 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, *third alm 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, </pre> | See above ... but for addressable sensors 33-48 |
| <pre> Address Chan 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 *Fault 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, *first alm 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, *second alm 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, *third alm 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, </pre> | See above ... but for addressable sensors 49-64 |
| <pre> 485Comms A/Cpower CanComms Battery :ev 0, 0, 0, 0, </pre> | Defines the local relay number driven when these events occur |
| <pre> 8 7 6 5 F O H L local energised relays :E 0 0 0 0 0 0 0 0 </pre> | Default state of mainboard relays: 0 = De-energised, 1= Energised |
| <pre> g f e d c b a 9 8 7 6 5 4 3 2 1 remote energised relays :R 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 </pre> | Default state of the first external 16 way relay board relays: 0 = Deenergised, 1= Energised |
| <pre> gfedcba987654321 Direct Fault relay patterns :h01,00000000000000000000 :h02,00000000000000000000 </pre> | (x16) these patterns are output to the first 16 of the external relays. See note 3 at start of appendix 2 pg 35 to see how to divert 7 of these relays. |
| <pre> gfedcba987654321 Direct Low Alarm relay patterns :i01,10000000000000000000 :i02,00000000000000000000 </pre> | (x16) As above but for Direct low alarms |
| <pre> gfedcba987654321 Direct High Alarm relay patterns :j01,00000000000000000000 :j02,00000000000000000000 </pre> | (x16) As above but for Direct High alarms |
| <pre> gfedcba987654321 Direct OverRange Alarm relay patterns :k01,00000000000000000000 :k02,00000000000000000000 </pre> | (x16) As above but for Direct Overrange alarms |
| <pre> gfedcba987654321 CAN Fault relay patterns *h01,00000000000000000000 *h02,00000000000000000000 </pre> | (x64) ... As above but for CAN Fault relay patterns |
| <pre> gfedcba987654321 CAN Low Alarm relay patterns *i01,00000000000000000000 *i02,00000000000000000000 </pre> | (x64) ... As above but for CAN Low Alarm relay patterns |
| <pre> gfedcba987654321 CAN High Alarm relay patterns *j01,00000000000000000000 *j02,00000000000000000000 </pre> | (x64) ... As above but for CAN High Alarm relay patterns |
| <pre> gfedcba987654321 CAN OverRange Alarm relay patterns *k01,00000000000000000000 *k02,00000000000000000000 </pre> | (x64) ... As above but for CAN OverRange Alarm relay patterns |
| <pre> gfedcba987654321 CAN bus Alarm relay patterns :n00000000000000000000 </pre> | As above but for CAN bus Alarm relay patterns |
| <pre> gfedcba987654321 Battery fail Alarm relay patterns :p00000000000000000000 </pre> | As above but for Battery fail Alarm relay patterns |
| <pre> gfedcba987654321 A/C fail Alarm relay patterns :q00000000000000000000 </pre> | As above but for A/C fail Alarm relay patterns |
| <pre> gfedcba987654321 485 bus Alarm relay patterns :r00000000000000000000 </pre> | As above but for 485 bus Alarm relay patterns |
| <pre> Delays for 16 remote relay patterns :d 1, 2, :d 2, 2, :d 3, 2, :d 4, 2, :d 5, 2, :d 6, 2, :d 7, 2, :d 8, 2, :d 9, 2, :d10, 2, :d11, 2, :d12, 2, :d13, 2, :d14, 2, :d15, 2, :d16, 2, </pre> | Delay in seconds to de-activate on first 16 relays of the optional 32way relay card (NOTE: 0 must NEVER be used as there is potential for a conflict in code. •0• can either mean 0 seconds to transition in state energise / de-energise (depending on default state) ie instantaneous •0• also means•does not occur• ... which means a change in state will never occur |
| <pre> Delay for 8 local relays :D 1, 1, :D 2, 1, :D 3, 1, :D 4, 1, :D 5, 1, :D 6, 1, :D 7, 1, :D 8, 1, </pre> | Delay in seconds on the 8 local relays (NOTE: 0 must NEVER be used as there is potential for a conflict in code. •0• can either mean 0 seconds to transition in state energise / de-energise (depending on default state) ie instantaneous •0• also means•does not occur• ... which means a change in state will never occur |
| :X, | End of text file. |

Appendix 3

Modbus Register Specification for COMBI 16 channel +CAN system

Function code 03 used throughout to access these 16 bit unsigned registers

Baud rate 4800,9600,19200

No parity

2 stop bits

2 channel known as Duty and standby

(RS485)

| | Register | definition | Data | Units |
|---------------|------------|-----------------------|----------------------------|---------------------------------|
| | 0 | watchdog counting | integer | none |
| | | | | int 250 usec counter |
| 4-20 chan | 1 to 16 | integer | Gas value * 10 | as per 17 to 32 |
| 4-20 chan | 17 to 32 | gas 1-16 units | see gas number table | units |
| | | | | will have zero for unused |
| 4-20 chan | 33 | low alarm bits | 1-16 channel | 1=alarm (bit 0 is chan 1 etc) |
| 4-20 chan | 34 | high alarm bits | 1-16 channel | 1=alarm (bit 0 is chan 1 etc) |
| 4-20 chan | 35 | overrange alarm bits | 1-16 channel | 1=alarm (bit 0 is chan 1 etc) |
| 4-20 chan | 36 | Sensor fail | 1-16 channel | 1=alarm (bit 0 is chan 1 etc) |
| Can Chan | 40 to 104 | integer | Gas value * 10 | as per 105 to 168 |
| Can Chan | 105 to 168 | gas 1-64 units | see gas number table | units will have zero for unused |
| Can Chan | 169 | low alarm bits | 1-16 channel | 1=alarm (bit 0 is chan 1 etc) |
| Can Chan | 170 | low alarm bits | 17-32 channel | 1=alarm (bit 0 is chan 17 etc) |
| Can Chan | 171 | low alarm bits | 33-48 channel | 1=alarm (bit 0 is chan 33 etc) |
| Can Chan | 172 | low alarm bits | 49-64 channel | 1=alarm (bit 0 is chan 49 etc) |
| Can Chan | 173 | high alarm bits | 1-16 channel | 1=alarm (bit 0 is chan 1 etc) |
| Can Chan | 174 | high alarm bits | 17-32 channel | 1=alarm (bit 0 is chan 17 etc) |
| Can Chan | 175 | high alarm bits | 33-48 channel | 1=alarm (bit 0 is chan 33 etc) |
| Can Chan | 176 | high alarm bits | 49-64 channel | 1=alarm (bit 0 is chan 49 etc) |
| Can Chan | 177 | over range alarm bits | 1-16 channel | 1=alarm (bit 0 is chan 1 etc) |
| Can Chan | 178 | over range alarm bits | 17-32 channel | 1=alarm (bit 0 is chan 17 etc) |
| Can Chan | 179 | over range alarm bits | 33-48 channel | 1=alarm (bit 0 is chan 33 etc) |
| Can Chan | 180 | over range alarm bits | 49-64 channel | 1=alarm (bit 0 is chan 49 etc) |
| Can Chan | 181 | Sensor fail | 1-16 channel | 1=alarm (bit 0 is chan 1 etc) |
| Can Chan | 182 | Sensor fail | 17-32 channel | 1=alarm (bit 0 is chan 17 etc) |
| Can Chan | 183 | Sensor fail | 33-48 channel | 1=alarm (bit 0 is chan 33 etc) |
| Can Chan | 184 | Sensor fail | 49-64 channel | 1=alarm (bit 0 is chan 49 etc) |
| | | item | | |
| | 222 | system status | bit 0 = global sensor fail | |
| | | | bit 1 = spare | |
| | | | bit 2 = system fault | |
| | | | bit 3 = battery power lost | |
| | | | bit 4 = main power lost | |
| | | | bit 5 = | |
| | | | bit 6 = | |
| | | | bit 7 = | |
| | | | bit 8 = modbus comms fail | |
| | | | bit 9 = I | |
| | | | bit 10 = CAN bus fail | |
| | | | bit 11 = spare | |
| | | | bit 12 = spare | |
| | | | bit 13 = spare | |
| | | | bit 14 = spare | |
| | | | bit 15 = spare | |
| Can Addresses | | | | |
| | 1 to 64 | | Can Sensors | |
| | 65 to 128 | | Reserved for more | |
| | 129 to 200 | | Spare | |
| | 201 to 209 | | Panels (default=201) | |
| | 210 to 255 | | Spare | |

Appendix 4

Event numbers are as follows:

| | |
|------------------|---------|
| chanfail | 0-15 |
| chanhialarm | 16-31 |
| chanloalarm | 32-47 |
| chanoralarm | 48-53 |
| Canchanfail | 54-69 |
| Canchanhialarm | 68-83 |
| Canchanloalarm | 84-99 |
| Canchanoralarm | 100-115 |
| main_power_alarm | 117 |
| can_bus_alarm | 118 |
| battery_alarm | 119 |
| clear_event_log | 120 |
| panelreset | 121 |

Appendix 5

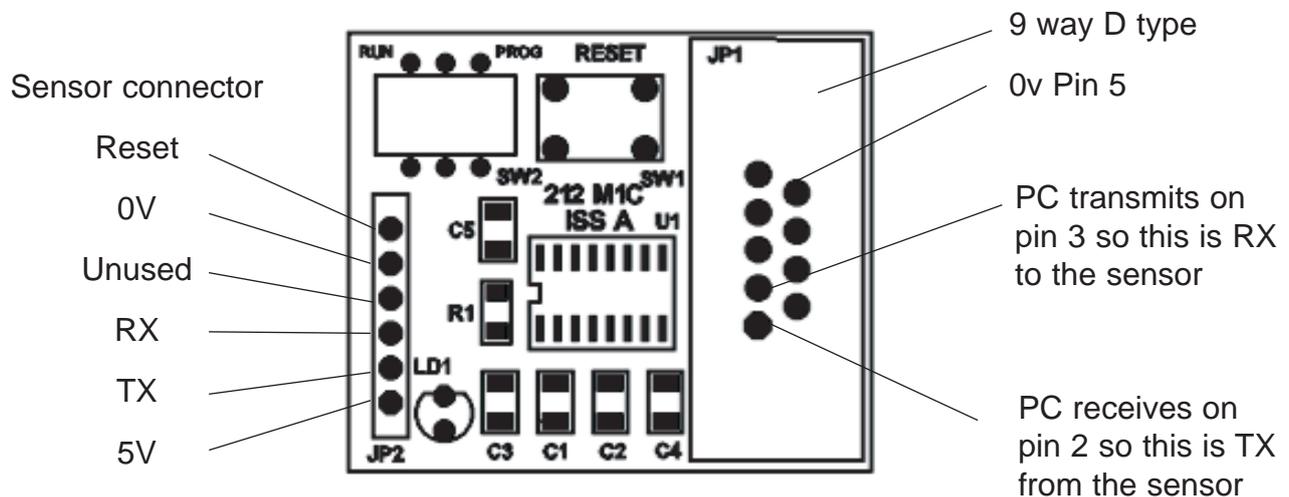
Fuse ratings

F1 ... Mains input 1A ... Anti-Surge

Fig. 1

PC adapter (converts sensor data output to RS232 for PC)

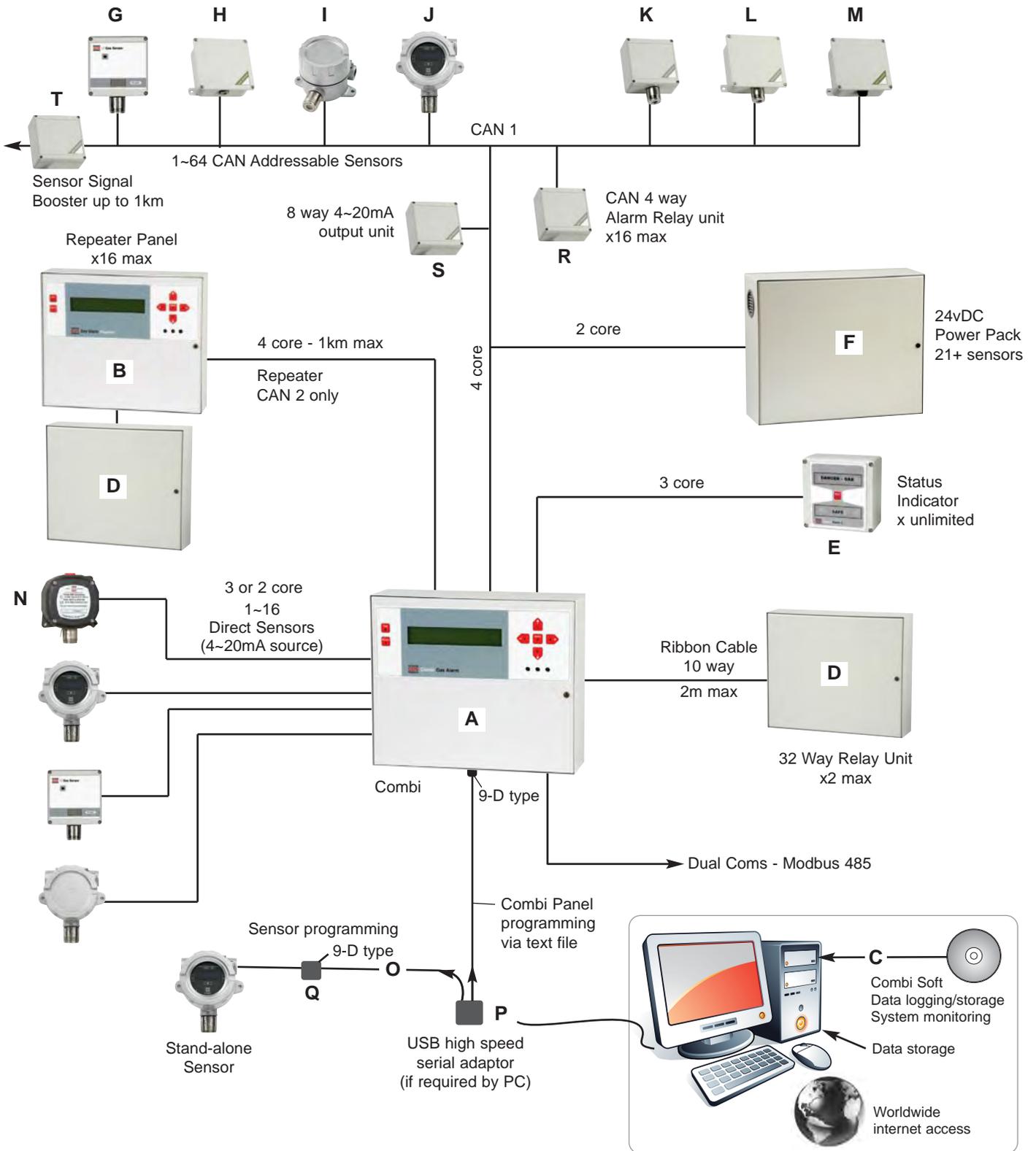
The 9 Way D-type plugs into the PC COM port and the pre-wired sensor connector is inserted into J3 on the Combi Flam PCB (198 Issue P) and J3 on the Combi Tox PCB (204 Issue N). When Hyper-terminal on the PC set at 4800 baud (no handshake) and connected to the com port, the PC should now display the continuous sensor output .



When programming the sensor processor, the Run and Prog slide switch SW2 is set to Prog but under normal circumstances, this switch should be in the Run position.

The Reset push button SW1 when pressed gives a hardware reset to the sensor processor. This can be pressed at any time and the sensor reacts in the same way as if it had reset itself.

Fig. 2 System Configuration



| Ref | Description | Part No |
|-----|---|---------|
| A | Combi Control Unit - 64 + 16 Sensors | 160-100 |
| B | Combi Repeater Panel | 160-200 |
| C | Combi 64 Way Data Logger Software | 160-500 |
| D | Combi Additional Relay Panel - 32 Way | 007-613 |
| E | Status Indicator II | 007-011 |
| F | Combi Auxiliary Power Pack 11A @ 24vDC (required for use with 21 or more sensors) | 200-003 |
| G | 20JF1 Flam / Toxic Gas Sensor SAFE AREA (Display) | |
| H | 40JF6 Flam / Toxic Gas Sensor SAFE AREA | |
| I | XDIF1 Flam / Toxic Gas Sensor HAZARDOUS AREA | |
| J | XDIWIN F1 Flam / Toxic Gas Sensor HAZARDOUS AREA | |

| Ref | Description | Part No |
|-----|--|---------|
| K | 20JF1 Flam / Toxic Gas Sensor SAFE AREA | |
| L | 40JF1 Flam / Toxic Gas Sensor SAFE AREA | |
| M | 40JP1 Toxic Gas Sensor SAFE AREA | |
| N | 9000JF1 Flam / Toxic Gas Sensor HAZARDOUS AREA | |
| O | RS232 Interface Adapter Lead | 160-515 |
| P | RS232 to USB Adapter Lead + Software | 160-520 |
| Q | RS232 Interface Adapter Unit | 160-510 |
| R | CAN Alarm Relay Module in 20JJB - 4 Relay | 160-205 |
| S | 8 way 4~20mA output signals | |
| T | Sensor Booster Unit | |

Fig. 3 Combi Controller Network Configuration

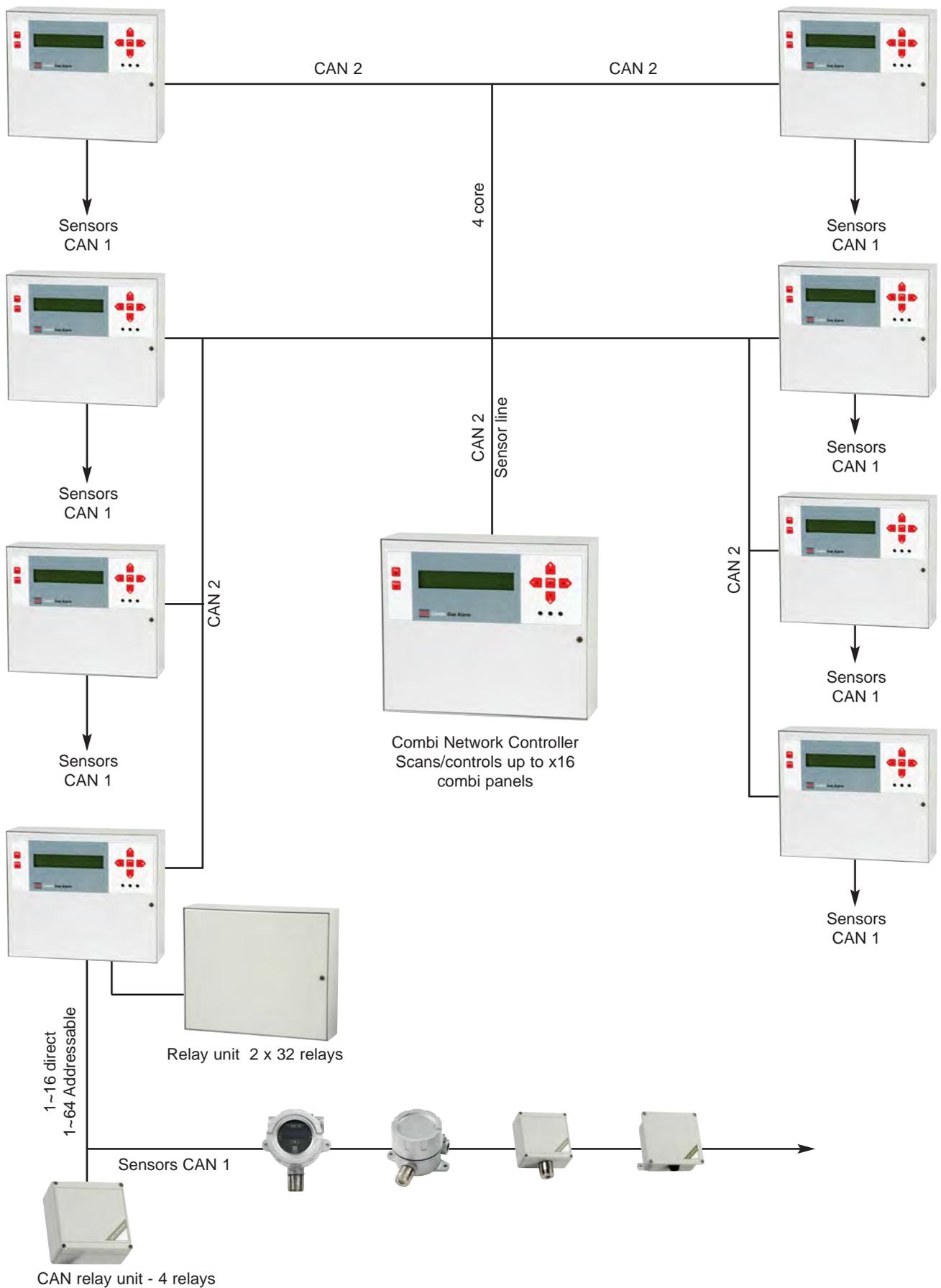
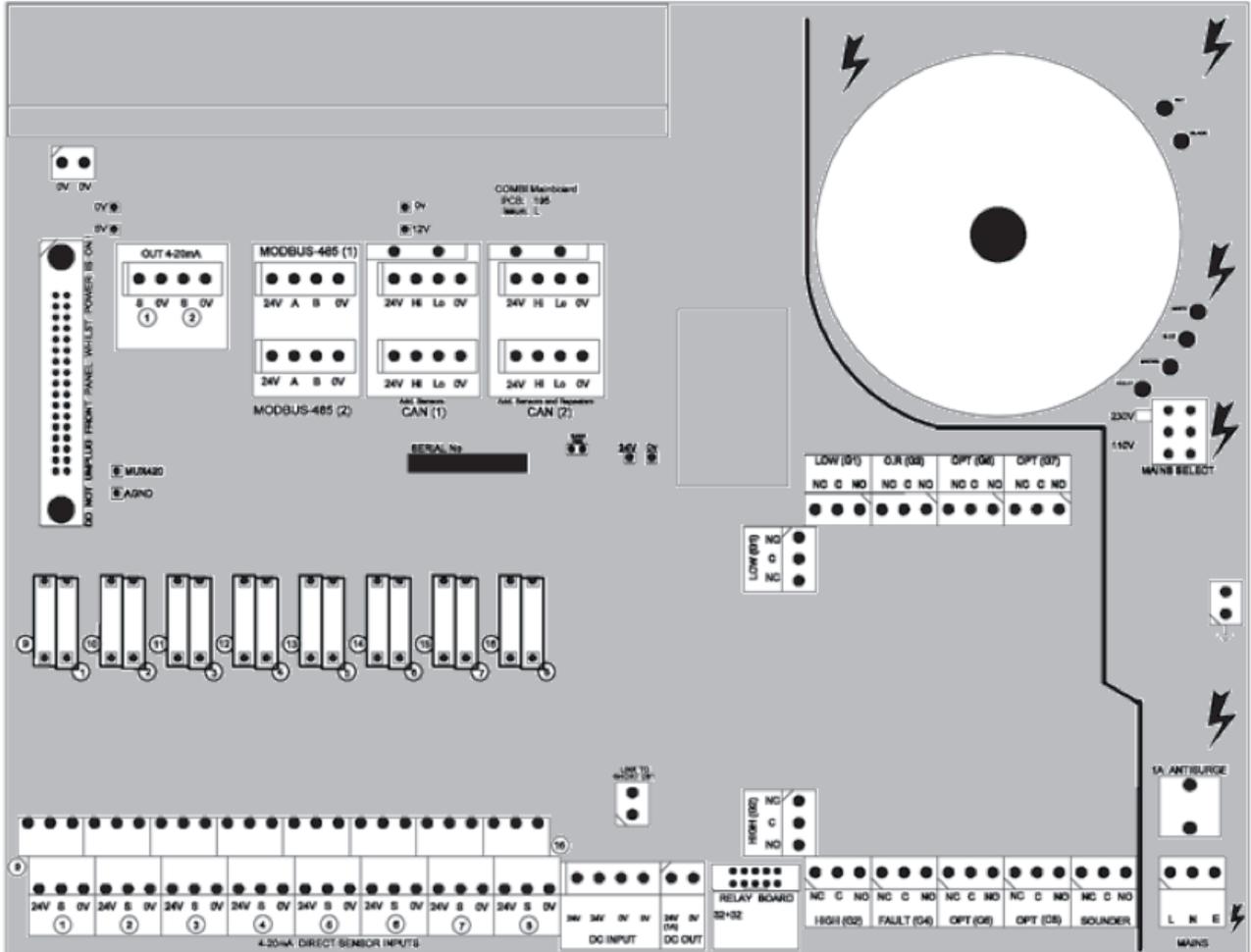


Fig. 4 Circuit Board details

Power supply and Input / Outputs



Front Panel PCB

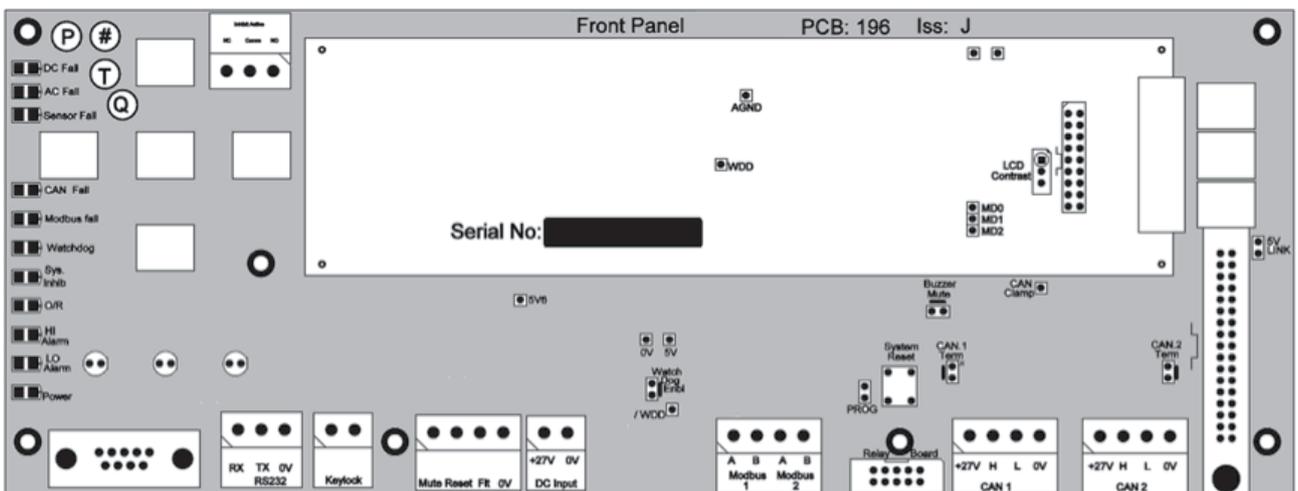
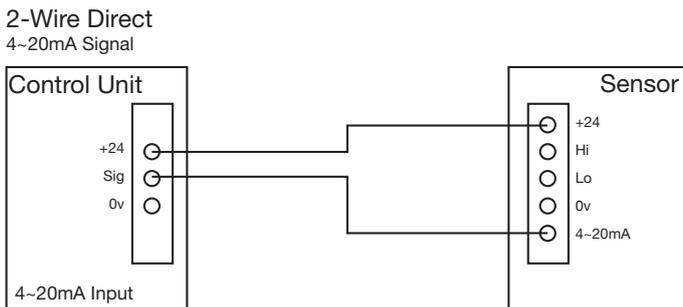
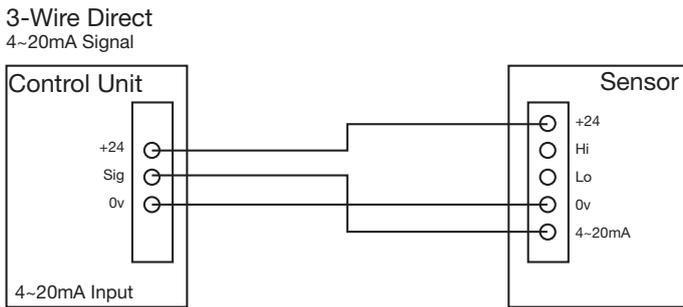
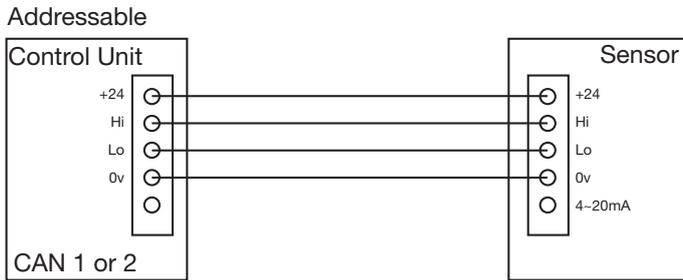


Fig. 5 System Wiring

Mainboard to Sensor wiring



Sensor Jumper configuration for TOX Board

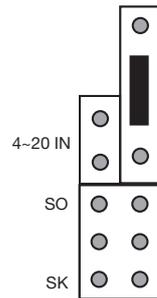
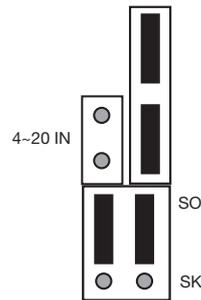
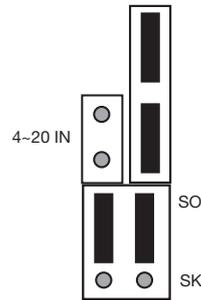
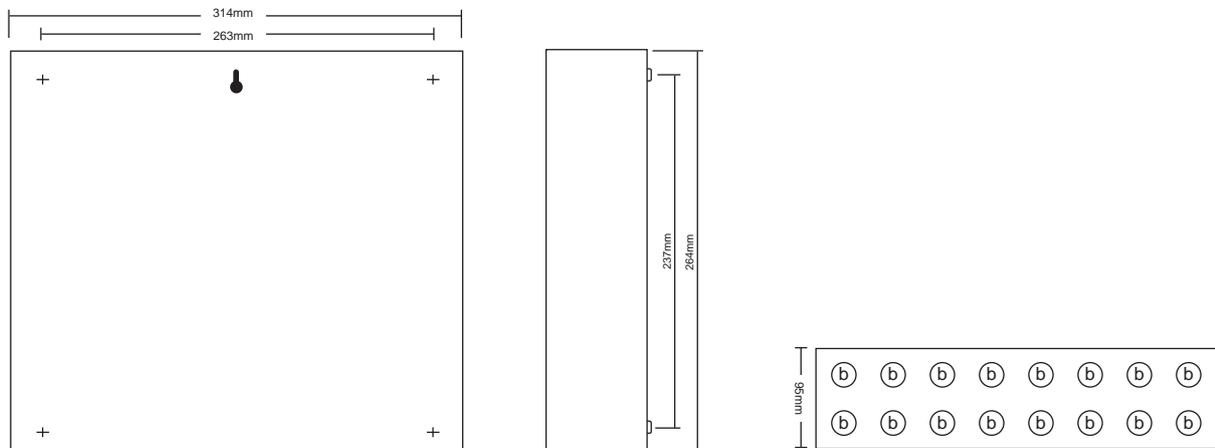


Fig. 6 Enclosure Detail



NEW SENSORS ARE SUPPLIED READY TO CONNECT TO THE SYSTEM.

The following procedure is for full set up but where only the sensor cell has been replaced - only sections 5, 6, 7, 9 and 11 need to be carried out. Voltage measurements are made wrt AG unless otherwise specified.

1. Insert jumpers J20 and J6 in position SO for 4-20mA source output.
2. Turn sensor voltage potentiometer RV4 fully anti-clockwise (minimum voltage).
3. Connect sensor to J2 terminal W-white P-pink Y-yellow.
4. Connect +24V and 0V to J10 and short the 4~20mA terminal by inserting test link at J9.
5. Measure the sensor voltage at SV and adjust by turning RV4 clockwise.
(standard sensor CAT300 = 2VDC.) **DO NOT EXCEED THE REQUIRED VOLTAGE OTHERWISE PERMANENT DAMAGE WILL OCCUR.**
6. Rotate RV2 fully anti-clockwise (minimum span.)
7. The sensor bridge is zeroed by adjusting RV3 until the dual colour LED D1 is off. (Or voltage VO is 0.0v)
8. Connect PC hyper terminal using RS232 Combi adaptor (part no. 160-510 and lead part no. 160-515) at 4800 baud connected to J3 and initialise the sensor using (C) calibration mode, then shift + (\$) command from the keyboard.
9. Using a digital mV meter measure across test pins TP8/9 and adjust RV1 for 4mA (zero) = 4mV
10. Then press (Z) on the PC to zero the reading.
11. Apply a known test gas to the sensor (56% LEL = 2.5% vol methane) for 1 minute at a flow rate of 1 litre to give a 13mA = 13mV across test pins TP8/9, if necessary adjust potentiometer 20mA pot RV2.
12. When using a PC press (S) to enter span mode and using (H) or (L) adjust the reading to 56% LEL.
13. Press (space) to exit span and then (X) to exit the calibration mode.

An example of continuous data output to the PC from a flammable sensor is shown opposite and is the format for all gas types.

O, **H** and **L** represents the Over Range, High and Low alarms respectively
D indicates if a duplicate address is detected
F indicates if a fault present

I indicates when this sensor has its alarms inhibited

Under the O H L the ^ ^ v represent the direction of the alarms. L is falling and H and O are rising. A (*) under the letter(s) OHLDFI represents a detected state so in this example the sensor would be in high alarm and a fault present. 'Gas val 35.6' represents the value of the gas present at the sensor head. Pressing (R) on the PC causes a reset to occur. Gas type with address and serial number are then output to the PC together with alarms and calibration date.

```

Flam %LEL
OHLDFI
^ ^ v
- * - - * - Gas val = 35.6
    
```

A full command list via PC is available by pressing the letter P on the PC keyboard.

| Command | Use | | |
|----------------------------|--|------------------------------|---|
| A = Set CAN address | Sets the CAN address | O = Set over range alarm | Sets the over range alarm threshold |
| G = Select gas type | Select the gas type from a list | P = List command | List these commands on screen |
| Z = Zero | Press when no gas on sensor to give zero | X = Exit calibration mode | Exit this PC mode |
| S = Span | Use when calibration gas applied, H and L change reading | \$ = Initialise this sensor | Use on new PCB to set gas type to Flam |
| D = Enter calibration date | Enter the calibration date | C = Clear sensor data logger | An internal data logger is wiped (not in use) |
| Y = Toggle auto zero | Auto zero is ON or OFF, small drift is cleared | U = Alarm direction | Sets rising or falling alarms |
| H = Set high alarm | Sets the high alarm threshold | R = Range | Allows a change in maximum value |
| L = Set low alarm | Sets the low alarm threshold | N = Decimal points | Toggles between 1 and 2 decimal places |
| | | E = Edit user gas text | Choose gas description |
| | | F = Toggle fault Input | External fault input contact can be disabled |
| | | B = Toggle deadband | turn deadband ON or OFF |

14. Connect the sensor to a Combi alarm panel and ensure that it reports in correctly.
Note:- Fit the end of line (EOL) link J1 if the sensor is to be installed at the end of the sensor cable.
15. If front panel display board is fitted via connector J5 and U12 adjust VR1 for LCD contrast.
16. Remove J9 test link for normal operation.
17. Insert link J12 to enable the bridge fault detection. (4-20mA output falls to 2mA in fault).
18. Ensure J29 address link is removed (this is only used when changing address from a Panel)

Using magnets (set up)

The Combi sensors which have an LCD display fitted also incorporate 3 reed switches which can be activated using external magnets through the glass window of the flameproof XDIwin enclosure. These magnets do not act instantly and have to be in close proximity to L, M and R on the front display for a few seconds to activate a software setup function.

The left magnet enters the auto zero ON or OFF menu. This allows small drift changes in the sensor to be compensated for but is not operational when the sensor readings are greater than 5% of full scale. Therefore auto zero is inactive when a larger gas reading is present. When the remove magnets message appears, move the left magnet away and then the display shows if auto zero is ON or OFF. The left magnet puts auto zero ON and the right magnet turns it OFF. With no magnets present, the display will return to normal and after a few seconds timeout.

The right magnet allows the CAN address of the sensor to be changed. When the address menu is displayed with a prompt to remove the magnet, and then the display shows the address and that the right magnet will decrease it whilst the left magnet will increase it. This is then stored in internal non-volatile memory and the display will automatically revert to normal operation.

The centre magnet is used to inhibit the sensor. As with the left and right magnet functions the display requests that you remove the magnet and then the state of inhibit appears on the LCD. the left magnet then puts the sensor into inhibit whilst the right magnet removes it. The amber LED on the front panel under the LCD flashes when the sensor is inhibited. When all magnets are removed, the display will revert to normal operation.

The left and right magnets together allow the calibration menu to be used.

Removing both magnets as instructed on the LCD presents the first part of this multi menu which is ZERO. With no gas present use the left magnet to increase the reading and the right magnet to decrease to achieve a zero reading on the displayed gas. A timer is displayed on the LCD and when this reaches 0, the next menu is displayed. This timer is 15 seconds approximately and is reset back each time a magnet is near. Waiting till timeout is acceptable but this timeout can be speeded up by placing a magnet near to the centre position.

SPAN is the next part of the menu and gas should be applied to the sensor at this time. The left magnet now increases the gain and the right magnet reduces gain. The actual sensor value can be seen on the display to rise or fall respectively.

LOW ALARM is the next menu and left and right magnets increase and decrease this value.

HIGH ALARM is next followed by OVER RANGE alarm.

The direction of the alarms is displayed as ^ for rising and v for falling but these can be changed using left and right magnets together.

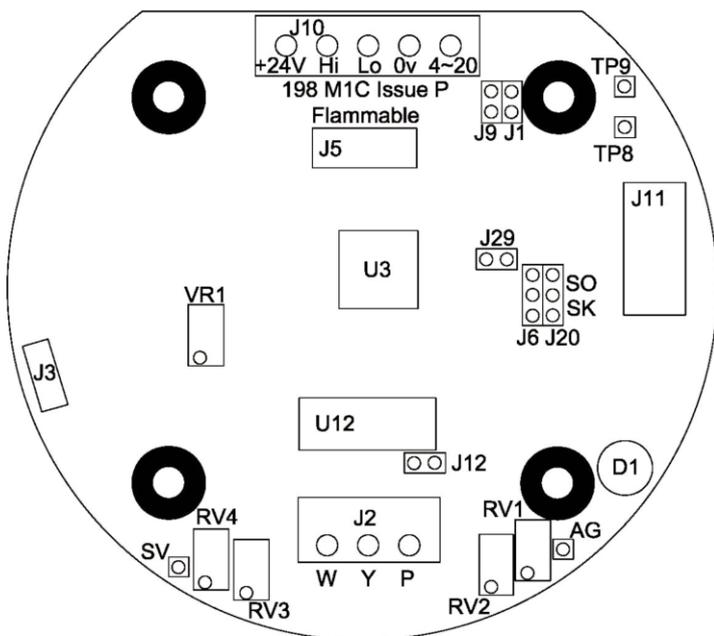


Fig. 1

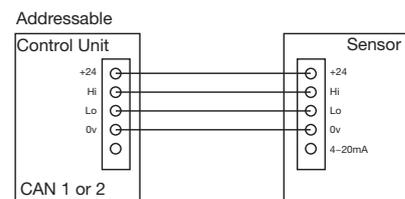


Fig. 2

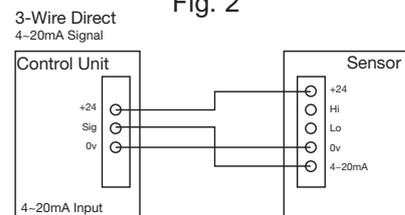


Fig. 3

NEW SENSORS ARE SUPPLIED READY TO CONNECT TO A SYSTEM WITH ALL JUMPERS INSERTED. THIS PROCEDURE SHOWS HOW TO RECALIBRATE AS PART OF ROUTINE MAINTENANCE OR CELL REPLACEMENT.

The first part is to set up the 4-20mA section which is produced by the CELL circuit. Note some cells take time to stabilise. If used as 2 wire then only steps 1 to 5 are required.

1. Connect the cell to terminal J2 and use +24V, 0V and 4~20mA connections on terminal J10 for 3wire (or +24V and 4~20mA for 2wire)
2. Measure voltage across test pins AG to Vo and adjust reading to zero mV using RV1 Offset pot
3. Measure the output current mV=mA at test pins TP1/TP2 and adjust reading to 4mV using RV3 4mA pot
4. Apply span gas to cell and adjust RV2 20mA pot to give correct mV reading at test pins TP1/TP2. NOTE: at 50% span gas, the mV reading at TP1/TP2 should be 12mV and the voltage across test pins AG and Vo should not exceed 1 volt so that 100% of range is achievable.
5. Remove the span gas and re-adjust 4mA pot RV3 to 4mV IF REQUIRED.

3 Wire with processor communications via CAN bus

6. With power applied ensure that MPU led is flashing and the CAN led is on or flashing.
7. Connect RS232 pod to J3 connector and to a PC running HyperTerminal at 4800 baud.
8. The terminal output screen shows continuous data output and allows input from the PC keyboard. Pressing •C• enters calibration mode
 - a. Press •SHIFT \$• to initialise the sensor and reset to default •Flam 100% LELŽ setting.
 - b. Then press •G• to change the gas type to match the cell being used.
NOTE: the range of the new gas has a default value but can be changed by pressing •R•.
 - c. Press •A• to change the address of this sensor if required
 - d. Press •N• to select the number of decimal places to 1 or 2, (ie: dp=1 or dp=2)
 - e. With no gas applied and 4mV measured at test pins TP8/TP9 press •Z• to zero the gas reading.
 - f. Then apply span gas and press •S• to enter span mode. The reading can be made HIGHER by pressing •H• or lower by pressing •L•
 - g. Pressing •SPACE BAR• will exit the span mode
 - h. Pressing •X• will exit the calibration mode.

Note: Oxygen cells only have two wires and connect to P+ and Y on terminal J2. To adjust for •zeroŽ it is normal practice to disconnect 1 wire from the cell and adjust the 4mA pot RV3 to get a 4mV reading across test pins TP8/TP9 for 3 wire sensor or test pins TP1/TP2 for 2 wire sensor. When the cell is reconnected in air at 20.9% oxygen the span can be adjusted for 17.3mV reading across the same test pins.

If an LCD option is fitted then calibration and other settings using magnets instead of a PC can be achieved as follows on next page.

Using magnets (set up)

The Combi sensors which have an LCD display fitted also incorporate 3 reed switches which can be activated using external magnets through the glass window of the flameproof XDIwin enclosure. These magnets do not act instantly and have to be in close proximity to L M and R on the front display for a few seconds to activate a software setup function.

The left magnet enters the Auto zero ON or OFF menu. This allows small drift changes in the sensor to be compensated for but is not operational when the sensor readings are greater than 5% of full scale. Therefore auto zero is inactive when a larger gas reading is present. When the remove magnets message appears, move the left magnet away and then the display shows if auto zero is ON or OFF. The left magnet puts auto zero on and the right magnet turns it off. With no magnets present, the display will return to normal after a few seconds timeout.

The right magnet allows the CAN address of the sensor to be changed. WHEN the ADDRESS menu is displayed with a prompt to remove the magnet, and then the display shows the address and that the right magnet will decrease it whilst the left magnet will increase it. This is then stored in internal non volatile memory and the display will automatically revert to normal operation.

The centre magnet is used to inhibit the sensor. As with the left and right magnet functions the display requests that you remove the magnet and then the state of the inhibit appears on the LCD. The left magnet then puts the sensor into inhibit whilst the right magnet removes it. An amber LED on the front panel under the LCD flashes when the sensor is inhibited. When all magnets are removed, the display will revert to normal operation.

The left and right magnets together allow the calibration menu to be used.

Removing both magnets as instructed on the LCD presents the first part of this multi menu which is ZERO. With no gas present use the left magnet to increase the reading and the right magnet to decrease to achieve a zero reading on the displayed gas. A timer is displayed on the LCD and when this reaches 0, the next menu is displayed. This timer is 15 seconds approximately and is reset back each time a magnet is near. Waiting till timeout is acceptable but this timeout can be speeded up by placing a magnet near to the centre position.

SPAN is the next part of the menu and gas should be applied to the sensor at this time.

The left magnet now increases the gain and the right magnet reduces gain. The actual sensor value can be seen on the display to rise or fall respectively.

Low alarm is the next menu and left and right magnets increase and decrease this value.

High alarm is next followed by over range alarm.

The direction of the alarms is displayed as ^ for rising and v for falling but these can be changed using left and right magnets together.

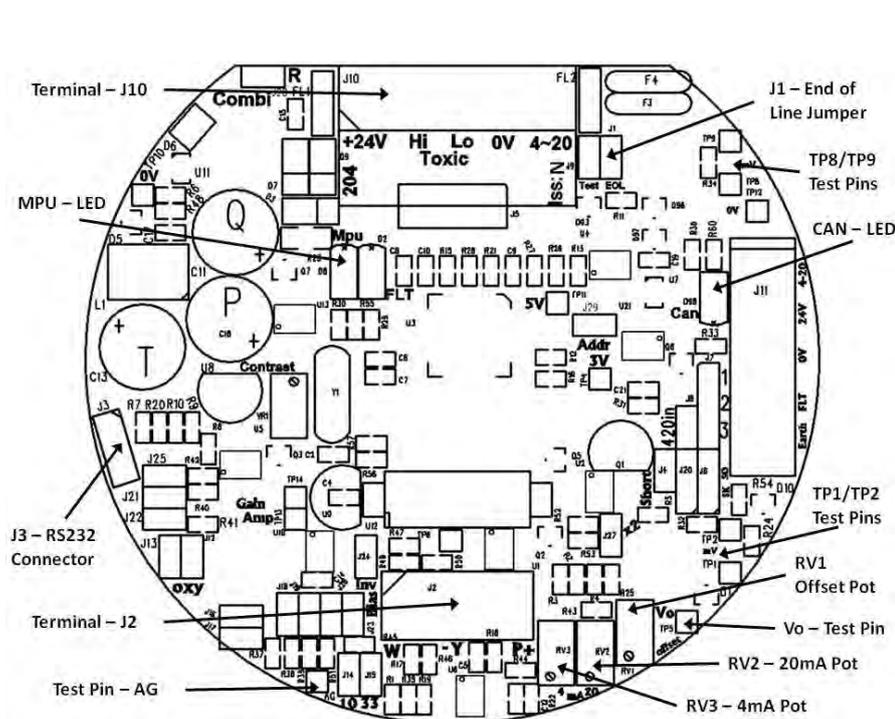
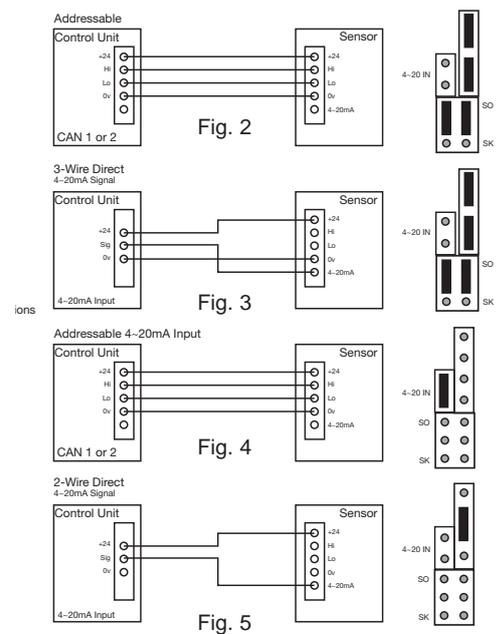


Fig. 1

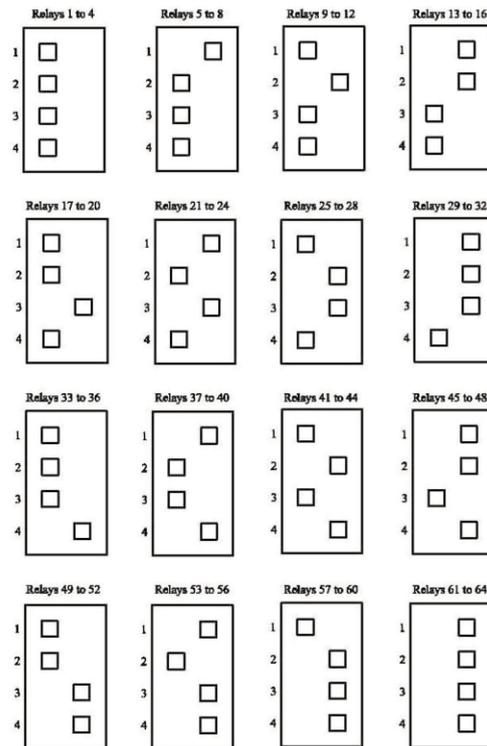
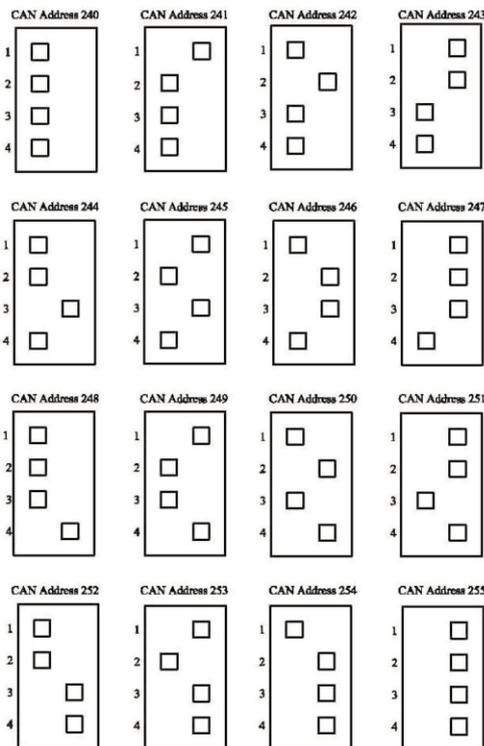


To allow the CAN relay to communicate with the Combi unit it must have a unique address between 240 and 255. This can be selected using the SW1 address switches. The selected address will be recognised by the Combi system automatically on power up. This can be checked in engineers menu 27 •Setup Network•.

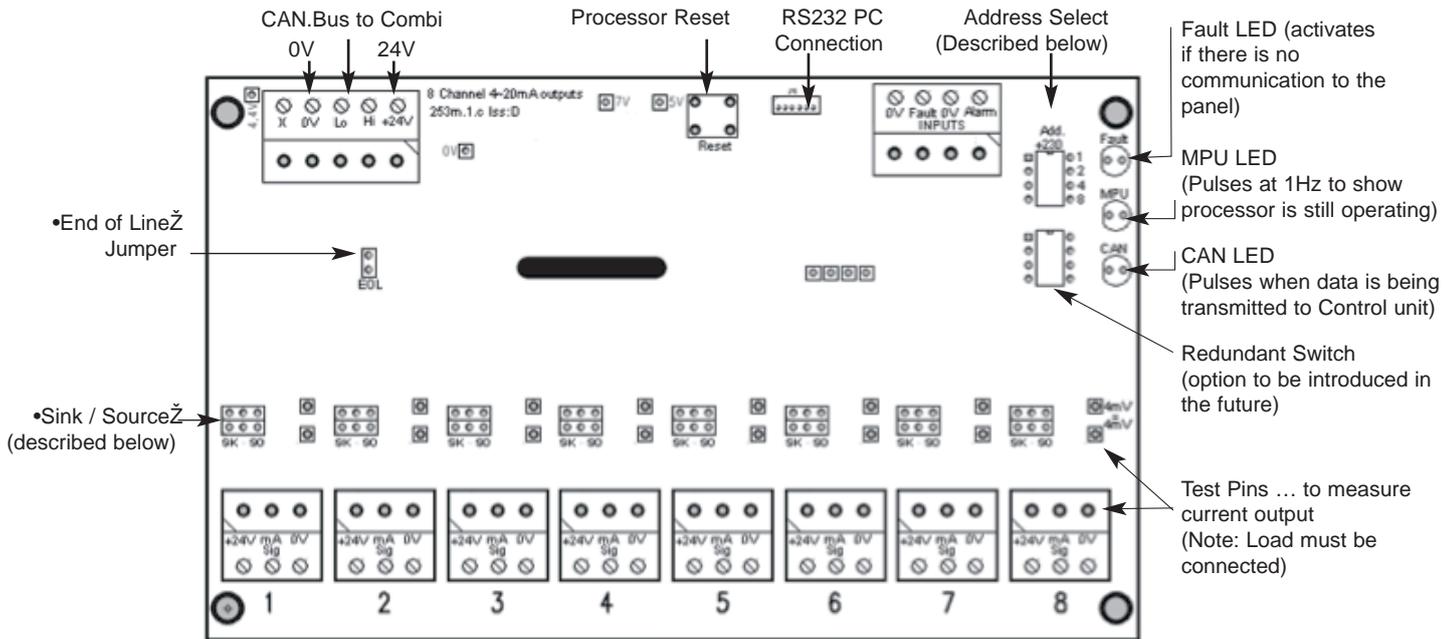
The CAN relay must also be set up to copy a group of 4 relays on one of two 32 way external relay boards. If a 32 way external relay unit is not being used the Combi system sees the 4 relays in the CAN relay as part of a virtual 32 way external board. SW2 is used to select which group of relays the CAN relay will copy.

CAN Address on SW1

4 relays copy external 32+32 relay PCB in groups of 4 using SW2



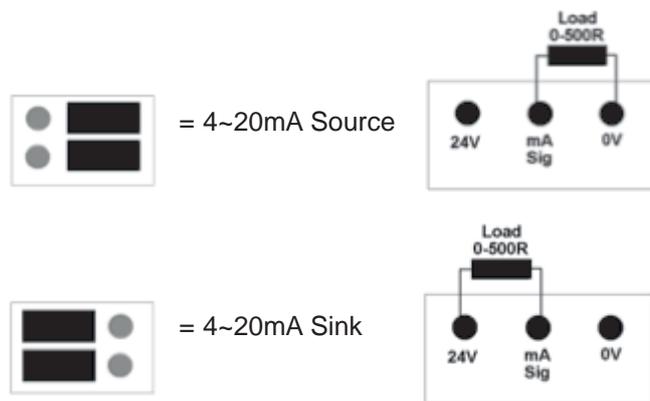
The eight channel 4~20mA output PCB allows signals in either sink or source mode to synchronised with the Combi 64 addressable and 16 direct sensors. By address selection on •S2Ž, the eight outputs can be selected for combinations of Combi sensors as detailed below.



The Combi detects the address being used on this card when connected to the CAN-bus. According to the address, the outputs represent the following:

- = Address: 230 = Direct sensors 1 ... 8
- = Address: 231 = Direct sensors 9 ... 16
- = Address: 232 = CAN sensors 1 ... 8
- = Address: 233 = CAN sensors 9 ... 16
- = Address: 234 = CAN sensors 17 ... 24
- = Address: 235 = CAN sensors 25 ... 32
- = Address: 236 = CAN sensors 33 ... 40
- = Address: 237 = CAN sensors 41 ... 48
- = Address: 238 = CAN sensors 49 ... 56
- = Address: 239 = CAN sensors 57 ... 64
- = Address: 240 = Highest in group 1 ... 8

Jumper configurations for Sink / Source mode:



NEW UNITS ARE SUPPLIED READY TO CONNECT TO A SYSTEM.
THE FOLLOWING PROCEDURE MAY NEED TO BE CARRIED OUT FOLLOWING CHANGES TO THE SYSTEM:

1. Insert J8 jumper to receive signal from external 4~20mA source (Fig.3)
2. Connect external 4~20mA source to the 4~20mA input terminal (J11) on the right hand side of the board.
3. Connect terminal J10 as shown in Fig.2
4. Ensure that the CAN LED is ON and flashing occasionally.
5. Connect RS232 pod to connector J3 and to a PC running HyperTerminal at 4800 baud.
6. The HyperTerminal display shows a continuous data output and allows input from the PC keyboard.
 - a. Press C to enter calibration mode
 - b. Press shift \$ to initialise the memory if new PCB (defaults to Flam %LEL)
 - c. Press G to change gas/signal to the type required for the cell/unit in use. (NOTE: When using a user gas press E to edit name before using G to select. Also make sure to select a vacant user gas number, 61-68, as the addressable sensor will overwrite data entered at the Combi panel.
 - d. The range of the gas/signal selected will have a default setting which can be changed by pressing R
 - e. Press A and enter CAN address of this sensor
 - f. Press N to toggle the number of decimal places between 1 and 2 (i.e. dp=1 or dp=2)
 - g. Press B to toggle the deadband ON and OFF
 - h. Press F to toggle the external fault option ON or OFF (only available when external source has local fault indication)
 - i. Press Z to zero the reading.
 - j. Press S to span the reading. Apply gas / signal from external source and press H or L to adjust the reading.
 - k. Press space to exit the span.
 - l. Press X to exit the calibration mode.
7. Connect to a combi panel and ensure that the sensor reports in correctly. **Note:** that if this sensor is at the end of the communication wires then it will need terminating by inserting jumper J1(EOL). The continuous data output when connected to HyperTerminal is the same format as for the Flammable sensor. The software used is identical.

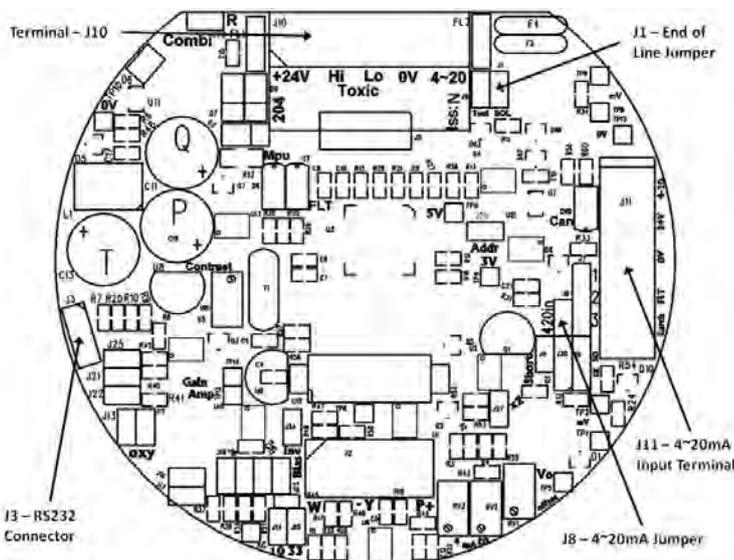


Fig. 1

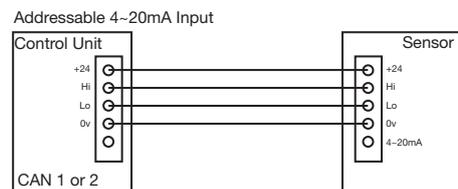


Fig. 2

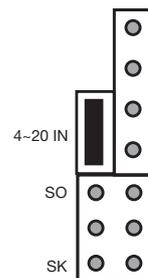


Fig. 3

C1123

| Main Controller | | | | Serial No. | | | | |
|-----------------|-----|------------|----------|------------|--------------------------|-----------|--------|-------|
| | | | | | Relay programmed or used | | | |
| Sensor No | Add | Direct I/P | Gas Type | Location | Common | CAN Relay | 32 Way | Group |
| 1 | | | | | | | | |
| 2 | | | | | | | | |
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